

I/A Series[®] Intelligent Pressure Transmitters

**IGP25 and IGP50 Gauge Pressure
with HART Communication**

Installation, Operation, Calibration, Configuration, and Maintenance

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1. Introduction

General Description

The IGP25-T and IGP50-T Intelligent Gauge Pressure Transmitters measure pressure by applying the pressure to a silicon strain gauge microsensor within the sensor assembly. This microsensor converts the pressure to a change in resistance, and the resistance change is converted to a 4 to 20 mA or digital signal proportional to the pressure. This measurement signal is transmitted to remote receivers over the same two wires that supply power to the transmitter electronics. These wires also carry two-way data signals between the transmitter and remote communication devices.

The transmitter allows direct analog connection to common receivers while still providing full Intelligent Transmitter Digital Communications using a HART Communicator.

The transmitter can be supplied with direct connected pressure seals or with remote pressure seals.

For more detailed information on the principle of operation of the transmitter, refer to document TI 037-096, available from Invensys.

Reference Documents

Table 1. Reference Documents

| Document | Description |
|--------------------|--|
| Dimensional Prints | |
| DP 020-217 | Dimensional Print – Pressure Transmitters with Pulp and Paper Process Connections |
| DP 020-218 | Dimensional Print – Pressure Transmitters with Sanitary Tri-Clamp Type Process Connections |
| DP 020-219 | Dimensional Print – Pressure Transmitters with Sanitary Mini Tank Spud Process Connections |
| DP 020-342 | Dimensional Print – PSFLT Pressure Seals |
| DP 020-343 | Dimensional Print – PSFPS and PSFES Pressure Seals |
| DP 020-345 | Dimensional Print – PSFAR Pressure Seals |
| DP 020-346 | Dimensional Print – PSFAD Pressure Seals |
| DP 020-347 | Dimensional Print – PSTAR Pressure Seals |
| DP 020-348 | Dimensional Print – PSTAD Pressure Seals |
| DP 020-349 | Dimensional Print – PSISR Pressure Seals |
| DP 020-350 | Dimensional Print – PSISD Pressure Seals |
| DP 020-351 | Dimensional Print – PSSCR Pressure Seals |
| DP 020-353 | Dimensional Print – PSSCT Pressure Seals |
| DP 020-354 | Dimensional Print – PSSSR Pressure Seals |

Table 1. Reference Documents (Continued)

| Document | Description |
|-----------------------|--|
| DP 020-355 | Dimensional Print – PSSST Pressure Seals |
| DP 020-447 | Dimensional Print – IAP10 and IAP20 Absolute Pressure and IGP10, IGP20, IGP25, and IGP50 Gauge Pressure Transmitters |
| Parts Lists | |
| PL 009-011 | Parts List – IGP25 Gauge Pressure Transmitter |
| PL 009-012 | Parts List – IGP50 Gauge Pressure Transmitter |
| Instructions | |
| MI 020-366 | Instruction – I/A Series Intelligent Pressure Transmitters Operation, Configuration, and Calibration Using a HART Communicator |
| MI 020-369 | Instruction – Pressure Seals |
| MI 020-427 | Instruction – Intrinsic Safety Connection Diagrams and Nonincendive Circuits |
| MI 020-501 | Instruction – PC50 Intelligent Field Device Tool (Installation and Parts List) |
| MI 020-520 | Instruction – PC50 Intelligent Field Device Tool with Advanced DTM Library (Operation Using HART Protocol) |
| MI 022-138 | Instruction – Bypass Manifolds - Installation and Maintenance |
| Technical Information | |
| TI 37-75b | Technical Information – Transmitter Material Selection Guide |
| TI 037-097 | Technical Information – Process Sealing of I/A Series Pressure Transmitters for use in Class 1, Zone 0, 1, and 2 Hazardous Locations |

Transmitter Identification

See Figure 1 for transmitter data plate contents. For a complete explanation of the Model Number code, see the parts list. The firmware version is identified on the top line of the display when **VIEW DB** (View Database) is selected in the top level structure. See Figure 2.

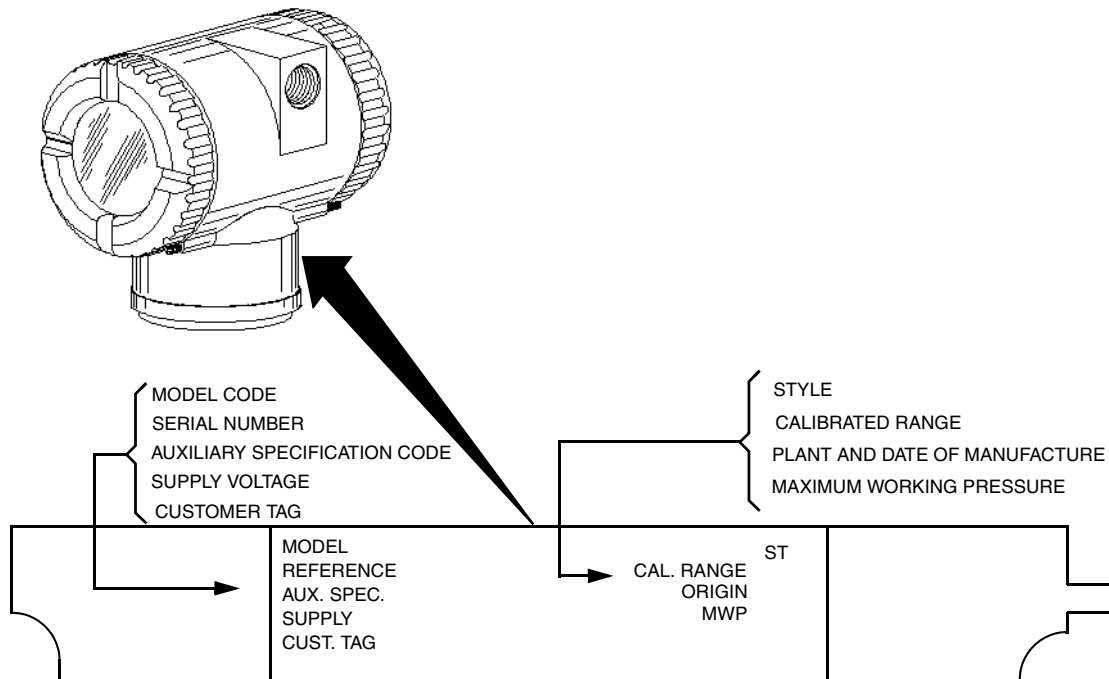


Figure 1. Transmitter Identification

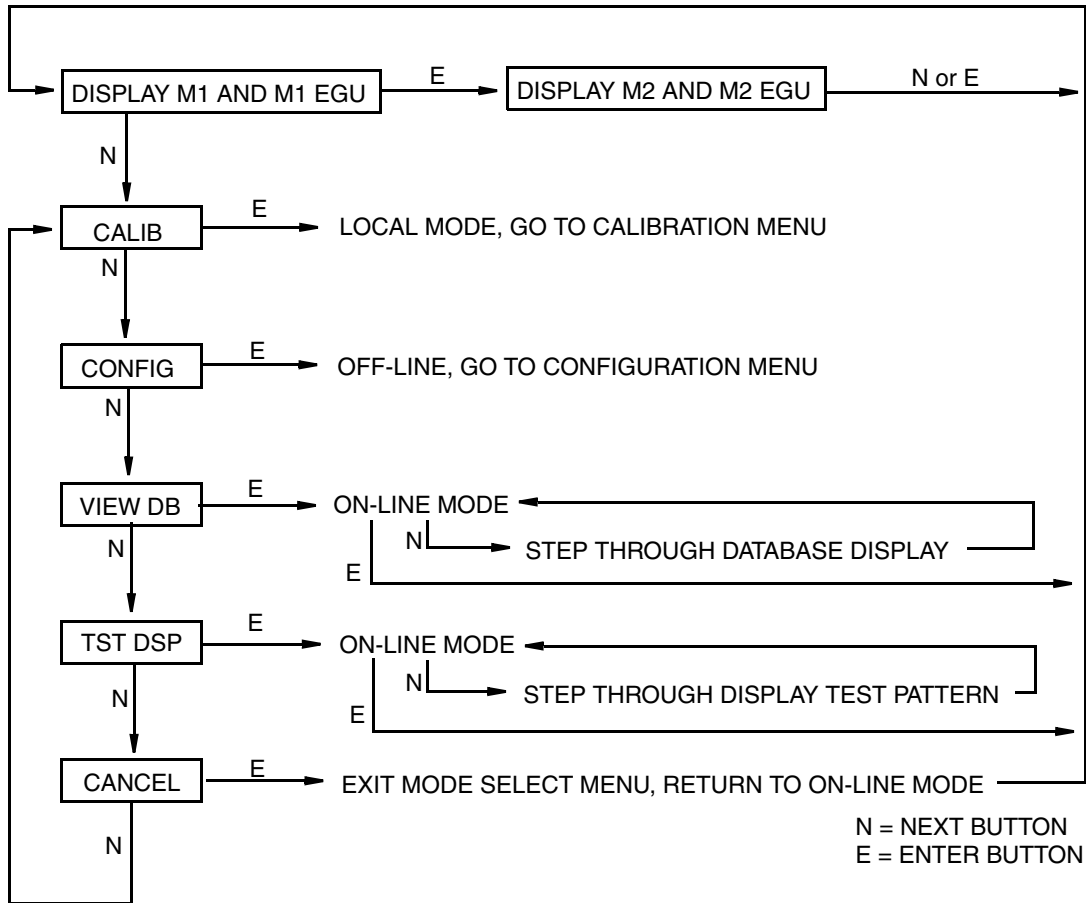


Figure 2. Top Level Structure Diagram

Standard Specifications

Operative Limits

| Influence | Operative Limits |
|--------------------------------|---|
| Sensor Body | |
| Temperature ^(a) | -46 and +121°C (-50 and +250°F) |
| Silicone Fill Fluid | -29 and +121°C (-20 and +250°F) |
| Fluorinert Fill Fluid | -18 and +121°C (0 and 250°F) |
| Neobee Fill Fluid | -7 and +82°C (20 and 180°F) |
| pvc Inserts | |
| Electronics Temperature | -40 and +85°C (-40 and +185°F) ^(b) |
| With LCD Display | -40 and +85°C (-40 and +185°F) ^(c) |
| Relative Humidity | 0 and 100% |
| Supply Voltage | 11.5 and 42 V dc |
| Output Load ^(d) | 0 and 1450 ohms |
| Mounting Position | No Limit |
| Vibration | 6.3 mm (0.25 in) double amplitude from 5 to 15 Hz with aluminum housing and from 5 to 9 Hz with 316 ss housing. 0 to 30 m/s (0 to 3 “g”) from 15 to 500 Hz with aluminum housing and 0 to 10 m/s (0 to 1 “g”) from 9 to 500 Hz with 316 ss housing. |

(a) Refer to MI 020-369 for temperature limits with pressure seals.

(b) -40 and +75°C (-40 and +167°F) for transmitters with ATEX flameproof classification.

(c) Display updates are slowed and readability decreased at temperatures below -20°C (-4°F).

(d) 250 Ω minimum load is required for communication with a HART Communicator.

Span and Range Limits

| Model | Span Limit Code | Span Limits | Range Limits |
|-------|-----------------|--------------------------------------|-------------------------------|
| IGP25 | D | 0.0035 and 1.4 MPa (0.5 and 200 psi) | 0 and 1.4 MPa (0 and 200 psi) |
| | E | 0.035 and 14 MPa (5 and 2000 psi) | 0 and 14 MPa (0 and 2000 psi) |
| IGP50 | D | 0.017 and 1.4 MPa (2.5 and 200 psi) | 0 and 1.4 MPa (0 and 200 psi) |
| | E | 0.17 and 14 MPa (25 and 2000 psi) | 0 and 14 MPa (0 and 2000 psi) |

Maximum Overrange Pressure and Proof Pressure

| Model | Span Limit Code | Maximum Overrange Pressure | Proof Pressure |
|-------|-----------------|----------------------------|-------------------|
| IGP25 | D | 2.1 MPa (300 psi) | 5.6 MPa (710 psi) |
| IGP50 | E | 21 MPa (3000 psi) | 56 MPa (7100 psi) |

! CAUTION

1. Exceeding the overrange pressure limit for the transmitter can cause damage to the transmitter, degrading its performance.
 2. The transmitter may be nonfunctional after application of the proof pressure.
-

Suppressed Zero

For applications requiring a suppressed zero, the span and range limits of the transmitter can not be exceeded.

Sensor Fill Fluid

Silicone Oil (DC 200) or Fluorinert (FC-43)

Mounting Position

The transmitter can be mounted in any orientation. It can be directly mounted to the process with either the direct connected or pipe mounted designs. The housing can be rotated up to one full turn to any desired position for access to adjustments, display, or conduit connections. See “Positioning the Housing” on page 20. The display (if present) can also be rotated in the housing to any of four different positions at 90° increments. See “Positioning the Display” on page 20.

NOTE

Position effect zero shift for all calibrated spans can be eliminated by readjusting zero output after installation.

Approximate Mass

1.5 kg (3.3 lb) with aluminum housing

Add 1.1 kg (2.4 lb) with 316 ss housing

Process Connections

IGP25 or IGP50 transmitters can be directly connected to the process using its 1/2 NPT external thread or optional G 1/2 B connection. If the optional mounting bracket is used, the transmitter can be connected to the process via the 1/2 NPT external thread, 1/4 NPT internal thread, or optional G 1/2 B connection.

Process Wetted Materials

Diaphragm: 316L ss

Process Connectors: 316L ss

Reference Pressure Side (Low Pressure Side) Materials

Silicon, Pyrex, RTV, and 316 ss

Electrical Connections

Field wires enter through 1/2 NPT, PG 13.5, or M20 threaded **entrances** on either side of the electronics housing. Leads terminate under screw terminals and washers on the terminal block in the field terminal compartment. To maintain RFI/EMI, environmental, and explosionproof ratings, unused conduit connection must be plugged with metal plug (provided), inserted to five full threads for 1/2 NPT connections; seven full threads for M20 and PG 13.5 connections.

Field Wiring Reversal

Accidental reversal of field wiring will not damage the transmitter, provided the current is limited to 1 A or less by active current limiting or loop resistance. Sustained currents of 1 A will not damage the electronics module or sensor but could damage the terminal block assembly and external instruments in the loop.

Adjustable Damping

The transmitter response time is normally 1.0 second or the electronically adjustable setting of 0.00 (none), 0.25, 0.50, 1, 2, 4, 8, 16, or 32 seconds, whichever is greater, for a 90% recovery from an 80% input step as defined in ANSI/ISA S51.1.

Output Signal

4 to 20 mA dc linear.

Zero and Span Adjustments

Zero and span are adjustable from the HART Communicator. They are also adjustable at the transmitter using the display. An optional external self-contained moisture sealed pushbutton assembly allows local resetting of zero without removing the housing cover.

Power-up Time

Less than 2.0 seconds for output to reach the first valid measurement, then at the electronic damping rate to reach the final measured variable value.

Supply Voltage

Power supply must be capable of providing 22 mA when the transmitter is configured for 4 to 20 mA output. Ripple of up to 2 V pp (50/60/100/120 Hz) is tolerable, but instantaneous voltage must remain within specified range.

The supply voltage and loop load must be within specified limits. This is explained in detail in “Wiring” on page 21. A summary of the minimum requirements is listed in the following table.

Table 2. Minimum Loop Load and Supply Voltage Requirements

| | HART Communication | No HART Communication |
|------------------------|-----------------------|--------------------------|
| Minimum Resistance | 250 Ω | 0 |
| Minimum Supply Voltage | 17 V | 11.5 V |

Electrical Ground Connections

The transmitter is equipped with an internal ground connection within the field wiring compartment and an external ground connection at the base of the electronics housing. To minimize galvanic corrosion, place the wire lead or contact between the captive washer and loose washer on the external ground screw. If shielded cable is used, earth (ground) the shield at the field enclosure **only**. Do **not** ground the shield at the transmitter.

HART Communicator Connection Points

The HART Communicator can be connected in the loop as shown in “Wiring” on page 21. It can also be connected directly to the transmitter at the two upper banana plug receptacles.

Test Points

The two lower banana plug receptacles (designated **CAL**) can be used to check transmitter output when configured for 4 to 20 mA. Measurements should be 100-500 mV dc for 0-100% transmitter output.

Remote Communications

The transmitter communicates bidirectionally over the 2-wire field wiring to a HART Communicator. The information that can be continuously displayed is:

- ◆ Process Measurement (expressed in one or two types of units)
- ◆ Transmitter Temperature (sensor and electronics)
- ◆ mA Output (equivalent)

The information that can be remotely displayed and reconfigured includes:

- ◆ Output in Pressure Units (linear). Percent output on local display is also supported.
- ◆ Zero and Span, including reranging
- ◆ Zero Elevation or Suppression
- ◆ Linear Output
- ◆ Pressure Units (from list provided)
- ◆ Temperature Sensor Failure Strategy
- ◆ Electronic Damping
- ◆ Poll Address (Multidrop mode)
- ◆ External Zero (Enable or Disable)
- ◆ Failsafe Direction
- ◆ Tag, Description, and Message
- ◆ Date of Last Calibration

Communications Format

Communication is based upon the FSK (Frequency Shift Keying) technique. The frequencies are superimposed on the transmitter power/signal leads.

4 to 20 mA Output

The transmitter sends its pressure measurement to the loop as a continuous 4 to 20 mA dc signal. It also communicates digitally with the HART Communicator at distances up to 3000 m (10 000 ft). Communication between the remote configurator and the transmitter does not disturb the 4 to 20 mA output signal. Other specifications are:

| | |
|-------------------------|--|
| Data Transmission Rate: | 1200 Baud |
| 4 - 20 mA Update Rate: | 30 times/second |
| Output when Fail Low: | 3.60 mA |
| Output when Fail High: | 21.00 mA |
| Output when Underrange | 3.80 mA |
| Output when Overage | 20.50 mA |
| Output when Offline: | User configurable between 4 and 20 mA |

Product Safety Specifications

— DANGER —

To prevent possible explosions and to maintain flameproof, explosionproof, and dust-ignitionproof protection, observe applicable wiring practices. Plug unused conduit opening with the provided metal pipe plug. Both plug and conduit must engage a minimum of five full threads for 1/2 NPT connections; seven full threads for M20 and PG 13.5 connections.

— WARNING —

To maintain IEC IP66/IP68 and NEMA Type 4X protection, the unused conduit opening must be plugged with the metal plug provided. Use a suitable thread sealant on both conduit connections. In addition, the threaded housing covers must be installed. Turn covers to seat the O-ring into the housing and then continue to hand tighten until the cover contacts the housing metal-to-metal.

— NOTE —

1. These transmitters have been designed to meet the electrical safety description listed in the table below. For detailed information or status of testing laboratory approvals/certifications, contact Invensys.
 2. Wiring restrictions required to maintain electrical certification of the transmitter are provided in “Wiring” on page 21.
-

Table 3. Electrical Safety Specifications

| Agency Certification, Types of Protection, and Area Classification | Application Conditions | Electrical Safety Design Code |
|---|--|-------------------------------|
| ATEX flameproof: II 2 GD EEx d IIC, Zone 1. | SIRA 04ATEX1349 Temperature Class T6 T85°C Ta = -40 to + 75°C | D |
| ATEX intrinsically safe: II 1 GD EEx ia IIC, Zone 0 or II 1/2 GD EEx ib IIC, Zone 0 and 1. | KEMA 00ATEX1009X Temperature Class T4 at 80°C, T5 at 40°C, and T6 at 40°C maximum ambient. | E |
| ATEX protection n: II 3 GD EEx nL IIC, Zone 2. | KEMA 00ATEX1060X Temperature Class T4 at 80°C, T5 at 70°C, and T6 at 40°C maximum ambient. | N |
| ATEX multiple certifications, ia & ib and n. Refer to Codes E and N for details. | Applies to Codes E and N but not to Code D. ^(a) | M |
| ATEX multiple certifications, ia & ib, d, and n. Refer to Codes D, E and N for details. | Applies to Codes D, E, and N. ^(a) | P |
| <p>CSA intrinsically safe for Class I, Division 1, Groups A, B, C, and D; Class II, Division 1, Groups E, F, and G; Class III, Division 1.</p> <p>Also zone certified intrinsically safe Ex ia IIC and energy limited Ex nA II.</p> | <p>Connect per MI 020-427. Temperature Class T4A at 40°C (104°F), and T3C at 85°C (185°F) maximum ambient.</p> <p>Temperature Class T4 at 40°C (104°F), and T3 at 85°C (185°F) max. ambient.</p> | C |
| CSA explosionproof for Class I, Division 1, Groups B, C, and D; dust-ignitionproof for Class II, Division 1, Groups E, F, and G; Class III, Division 1. | Maximum Ambient Temperature 85°C (185°F). | |
| CSA for Class I, Division 2, Groups A, B, C, and D; Class II, Division 2, Groups F and G; Class III, Division 2. | Temperature Class T4A at 40°C (104°F), and T3C at 85°C (185°F) maximum ambient. | |
| CSA field device zone certified flameproof Ex d IIC. Also, all certifications of Code C above. | Maximum Ambient Temperature 85°C (185°F). | B |

Table 3. Electrical Safety Specifications (Continued)

| Agency Certification, Types of Protection, and Area Classification | Application Conditions | Electrical Safety Design Code |
|---|--|-------------------------------------|
| <p>CSA intrinsically safe for Class I, Division 1, Groups A, B, C, and D; Class II, Division 1, Groups E, F, and G; Class III, Division 1.</p> <p>Also zone certified intrinsically safe Ex ia IIC and energy limited Ex nA II.</p> | <p>Connect per MI 020-427. Temperature Class T4A at 40°C (104°F), and T3C at 85°C (185°F) maximum ambient.</p> <p>Temperature Class T4 at 40°C (104°F), and T3 at 85°C (185°F) max. ambient.</p> | L (IGP25 only) |
| <p>CSA Class I, Division 2, Groups A, B, C, and D; Class II, Division 2, Groups F and G; Class III, Division 2.</p> | <p>Temperature Class T4A at 40°C (104°F), and T3C at 85°C (185°F) maximum ambient.</p> | |
| <p>FM intrinsically safe for Class I, Division 1, Groups A, B, C, and D; Class II, Division 1, Groups E, F, and G; Class III, Division 1.</p> <p>Also zone certified intrinsically safe AEx ia IIC.</p> | <p>Connect per MI 020-427. Temperature Class T4A at 40°C (104°F) and T4 at 85°C (185°F) maximum ambient.</p> <p>Temperature Class T4 at 85°C (185°F) maximum ambient.</p> | F |
| <p>FM explosionproof for Class I, Division 1, Groups B, C, and D; dust-ignitionproof for Class II, Division 1, Groups E, F, and G; Class III, Division 1.</p> | <p>Temperature Class T6 at 80°C (176°F) and T5 at 85°C (185°F) maximum ambient.</p> | |
| <p>FM nonincendive for Class I, Division 2, Groups A, B, C, and D; Class II, Division 2, Groups F and G; Class III, Division 2.</p> | <p>Temperature Class T4A at 40°C (104°F) and T4 at 85°C (185°F) maximum ambient.</p> | |
| <p>FM field device zone certified flameproof AEx d IIC. Also, all certifications of Code F above.</p> | <p>Temperature Class T6 at 75°C (167°F) maximum ambient.</p> | G |
| <p>FM intrinsically safe for Class I, Division 1, Groups A, B, C, and D; Class II, Division 1, Groups E, F, and G; Class III, Division 1.</p> <p>Also zone certified intrinsically safe AEx ia IIC.</p> | <p>Connect per MI 020-427. Temperature Class T4A at 40°C (104°F) and T4 at 85°C (185°F) maximum ambient.</p> <p>Temperature Class T4 at 85°C (185°F) maximum ambient.</p> | R (IGP25 only) |
| <p>FM nonincendive for Class I, Division 2, Groups A, B, C, and D; Class II, Division 2, Groups F and G; Class III, Division 2.</p> | <p>Temperature Class T4A at 40°C (104°F) and T4 at 85°C (185°F) maximum ambient.</p> | |
| <p>SAA Ex ia IIC, intrinsically safe, Gas Group IIC, Zone 0.</p> | <p>Temperature Class T4 at 85°C (185°F) maximum ambient.</p> | H |

Table 3. Electrical Safety Specifications (Continued)

| Agency Certification, Types of Protection, and Area Classification | Application Conditions | Electrical Safety Design Code |
|--|---|-------------------------------------|
| SAA Ex n IIC, nonincendive, Gas Group IIC, Zone 2. | Temperature Class T6. | K |
| IECEX flameproof: Ex d IIC, Zone 1. | IECEX SIR 05.0003X Temperature Class T6, Ta = -40 to +75°C | V |

(a) User must permanently mark (check off in rectangular block on data plate) one type of protection only (ia and ib, d, or n). This mark cannot be changed once it is applied.

ATEX and IECEX Warnings

Do not open while circuits are alive.

ATEX Compliance Documents

EN 50014: 1997 (inc amendments A1 and A2)
 EN 50018: 2000 (inc amendment A1)
 EN 50020: 1994
 EN 50281-1-1: 1998
 EN 50284: 1999
 EN 50021: 1999

IECEX Compliance Documents

IEC 60079-0 (Edition 3.1): 2000
 IEC 60079-1 (Edition 5): 2003

2. Installation

! CAUTION

To avoid damage to the transmitter sensor, do not use any impact devices, such as an impact wrench or stamping device, on the transmitter.

NOTE

1. The transmitter should be mounted so that any moisture condensing or draining into the field wiring compartment can exit through one of the two threaded conduit connections.
 2. Use a suitable thread sealant on all connections.
-

Transmitter Mounting

The IGP25 and IGP50 Transmitters with the 1/2 NPT external thread can be directly connected to the process or mounted to a vertical or horizontal pipe or a surface using the optional mounting set. See Figure 3.

For dimensional information, refer to DP 020-447.

NOTE

1. Do **not** directly mount the transmitters to the process using the 1/4 NPT internal thread. This thread should only be used to connect to the process when the transmitter is mounted with the optional mounting set.
 2. Do **not** mount the transmitters using the conduit connection and optional mounting set when vibration conditions exceed 20 m/s^2 (2 “g”).
 3. If the transmitter is not installed in the vertical position, readjust the zero output to eliminate the position zero effect.
-

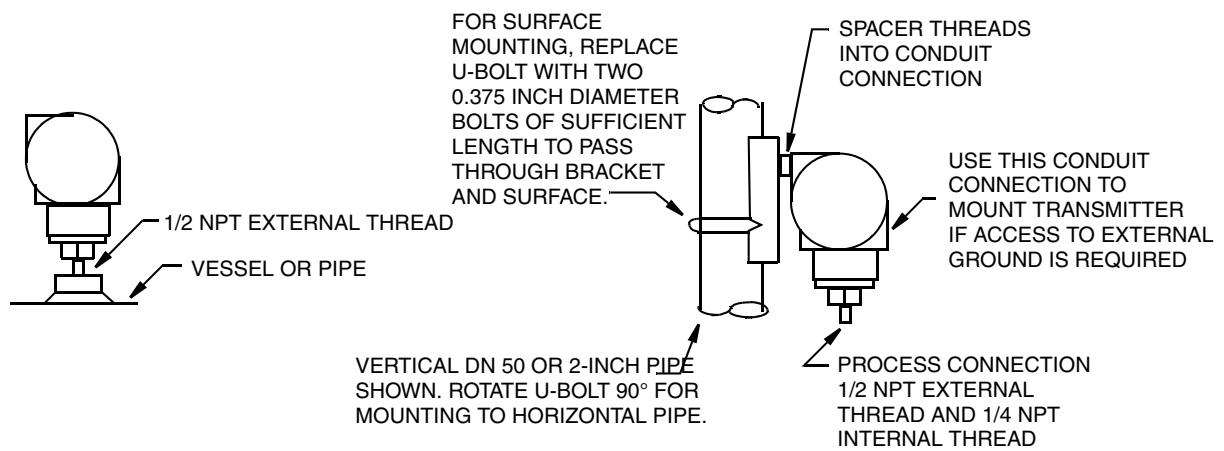


Figure 3. IGP25 and IGP50 Transmitter Mounting

Sanitary Process Connection

The IGP25 transmitters with a sanitary process connector employ a Tri-Clamp type connection or mini tank spud seal. Install the transmitter as shown in Figures 4 and 5. For dimensional information, see the following documents:

Tri-Clamp Type Connector: DP 020-218

Mini Tank Spud Connector: DP 020-219

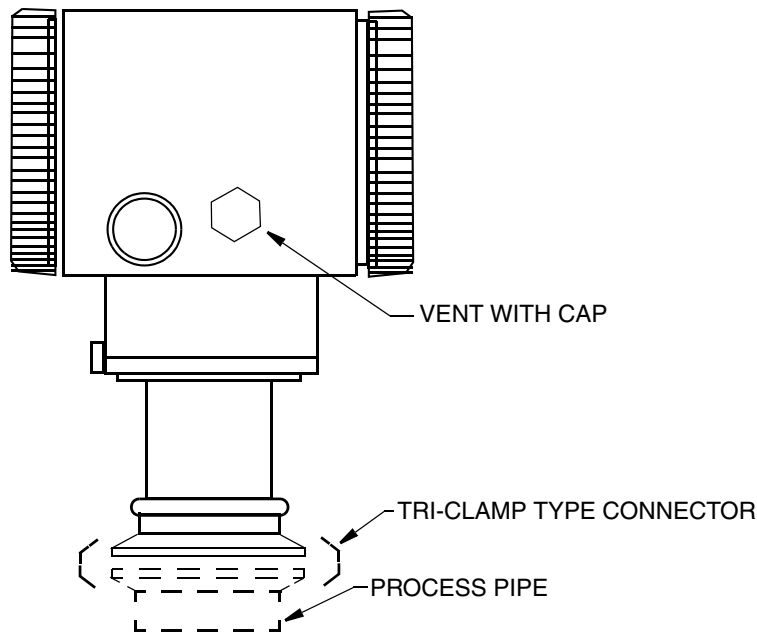


Figure 4. Mounting of Transmitter with Sanitary Tri-Clamp Type Connection

NOTE

If the transmitter is to be mounted horizontally (side of a tank), the housing should be oriented so that the vent is self draining. **Do not mount the vent facing up.**

If the vent is to face down, it is recommended that the protective cap be removed.

If the vent clogs, replace it with Foxboro Part Number D0186DQ (W.L.Gore part number PMF100318). It is recommended that spare vents be stocked and replaced at a predetermined interval as part of preventive maintenance. When installing a new vent, the applied torque should be 0.6 to 0.8 N•m (5 to 7 in•lb).

If the transmitter is subject to routine wash down such as in typical sanitary applications and the vent is orientated so that it is self draining, the vent will stay clear and longer intervals between preventive maintenance may be realized.

If the vent becomes clogged, the resulting pressure measurement error may be as much as 1.5 inH₂O per degree C change in temperature. This error is positive with decreasing temperature and negative with increasing temperature.

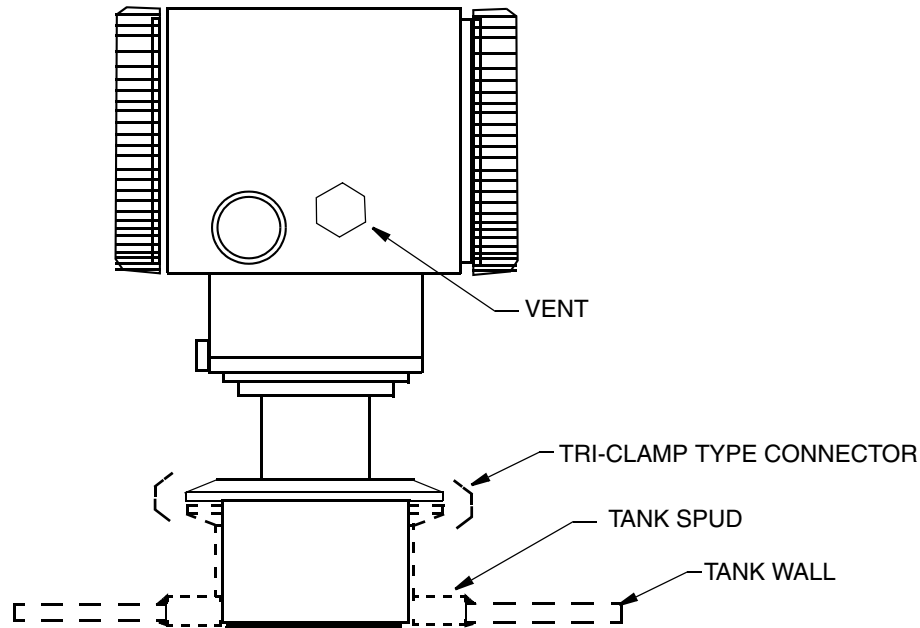


Figure 5. Mounting of Transmitter with Sanitary Mini Tank Spud Seal

The tank spud must be welded into a hole cut in the tank as follows:

1. Cut a hole into the process vessel to accept the spud. The spud should fit snugly and uniformly. The nominal diameter of the spud is: 3.73 inch (94.7 mm). To assure that the seal is always covered by process fluid, the top of the hole should be below the minimum measurement level.
2. Position the spud mounting ring so that it aligns as close as possible with the inside wall of the tank and that the weep hole is at the bottom.
3. Tack weld the spud mounting ring to the outside of the tank in four places.
4. Weld the spud mounting ring to the inner surface of the tank per the following notes.

— **NOTE** —

1. Spud is 316 stainless steel. Use compatible welding rod. Do not distort spud mounting ring by using excessive heat.
 2. Weld the spud mounting ring in sections as indicated in Figure 6.
 3. After each section is welded, cool right away with water until the temperature is less than 700°F (370°C) before welding the next section.
-
5. Grind the weld smooth so that the surface is free from irregularities where dirt can lodge.
 6. Outer surface can be welded if desired after inner weld is completed.

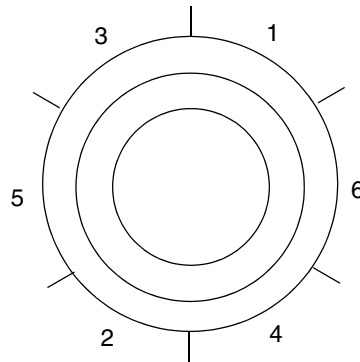


Figure 6. Welding Procedure

Pulp and Paper Process Connection

The IGP25 transmitters with a pulp and paper process connector are available in two designs - sleeve type and threaded type. Install the transmitter as explained below. For dimensional information, see DP 020-217.

Sleeve Type Connector

1. Cut a hole into the process vessel to accept the weld spud. The spud should fit snugly and uniformly. The nominal diameter of the spud is:
For nominal 1 inch connector: 1.32 inch (33.4 mm)
For Nominal 1 1/2 inch connector: 1.90 inch (48.3 mm)
2. Position the sleeve into the hole so that it aligns as close as possible with the inside wall of the vessel
3. Tack weld using the welding sequence shown in Figure 6. Cool each section with water until the temperature is below 700°F (370°C) before proceeding to the next section.
4. Weld the circumference of the sleeve using compatible stainless steel welding rod.

— NOTE

The welder should meet the requirements of ANSI B31.3, ASME Section IX or other codes, if applicable.

5. Lubricate the O-ring with appropriate lubricant and install it into the sleeve, ensuring that it is properly seated.

— NOTE

If the gasket is not properly seated, a process leak may occur.

6. Insert the transmitter sensor into the sleeve and hold it in place with cap screws.

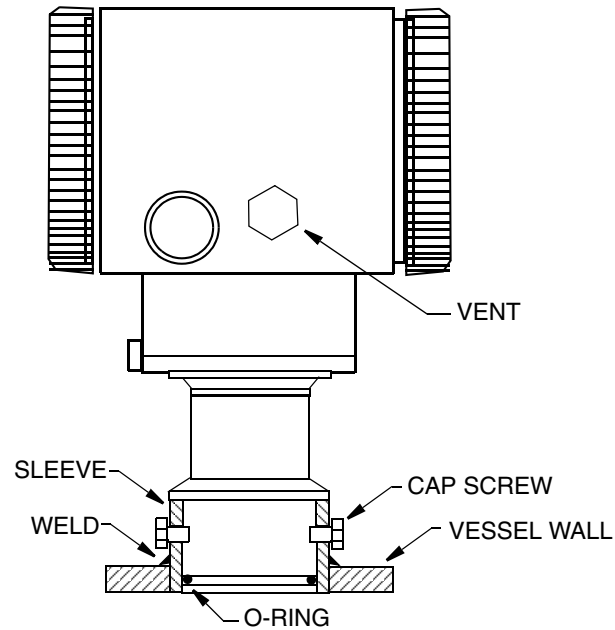


Figure 7. Mounting of Transmitter with Sleeve Type Pulp and Paper Process Connection

Threaded Type Connector

1. Cut a hole into the process vessel to accept the weld spud. The spud should fit snugly and uniformly. The nominal diameter of the spud is:
 For nominal 1 inch connector: 1.50 inch (38.1 mm)
 For nominal 1 1/2 inch connector: 2.38 inch (60.3 mm)
 For nominal 1 1/2 inch connector for Ametek spud: 1.99 inch (50.5 mm)
 Position the connector into the hole so that it aligns as close as possible with the inside wall of the vessel
2. Tack weld using the welding sequence shown in Figure 6. Cool each section with water until the temperature is below 700°F (370°C) before proceeding to the next section.

NOTE

Invensys recommends using a heat sink during this operation.

1 inch size: Part Number N1214YS

1 1/2 inch size: Part Number N1214YR

3. Weld the circumference of the connector using compatible stainless steel welding rod.

NOTE

The welder should meet the requirements of ANSI B31.3, ASME Section IX or other codes, if applicable.

4. After the connector has cooled, remove the heat sink.
5. Lubricate the gasket with appropriate lubricant and install it into the connector, ensuring that it is properly seated.

— NOTE

If the gasket is not properly seated, a process leak may occur.

6. Thread the sensor into the connector hand tight. Then tighten approximately 1/8 turn more.

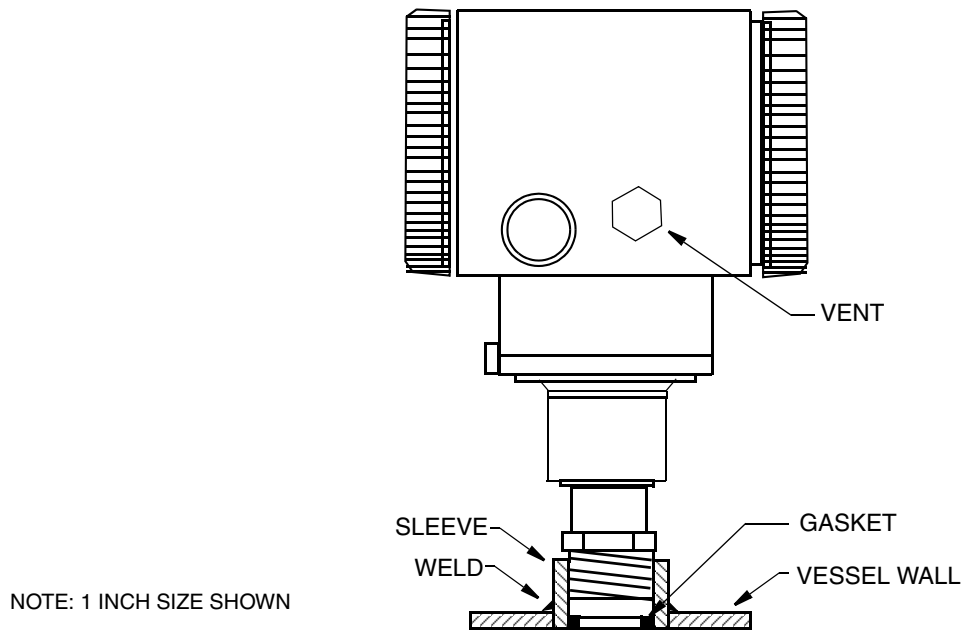


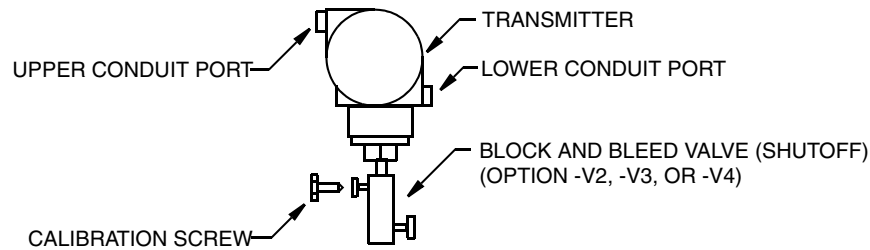
Figure 8. Mounting of Transmitter with Threaded Type Pulp and Paper Process Connection

Typical Transmitter Piping

Figure 9 shows a typical piping application. Calibration supply pressure can be applied via a calibration tee or calibration screw. The lower conduit port can be used as a drain for moisture buildup in terminal compartment.

— NOTE

1. 1. Invensys recommends the use of snubbers in installations prone to high levels of fluid pulsations.
 2. 2. Transmitters mounted directly to process piping or a pressure vessel, could require the use of a shutoff valve (shown) to comply with the requirements of ASME Power Piping Code B31.1 and Chemical and Petroleum Piping Code B31.3.
-



NOTE: Block and Bleed Valve Maximum Pressure
 40 MPa (6000 psi at 38°C) (100°F)
 25 MPa (4000 psi at 250°C) (400°F)
 Calibration Screw Maximum Pressure
 0.7 MPa (100 psi with Poly-Flo Fitting) (F0101ES)

Figure 9. Typical Transmitter Piping

For hot process applications above the operative limits of your transmitter [121°C (250°F) for silicone fill fluid or 82°C (180°F) for fluorinert fill fluid], such as steam, additional piping is required to protect the transmitter from the hot process. See Figure 10. The piping is filled with water or process fluid. Mount the transmitter below the pressure connection at the pipe. Although the transmitter is shown mounted vertically, you can also mount it horizontally unless sediment is present. The calibration tee is not required if a calibration screw is used for field calibrations.

If trapped vapor pockets cannot be tolerated in a liquid service and a horizontal process connection is used, install a pipe elbow and vertically position the transmitter with the housing **below** the process connection.

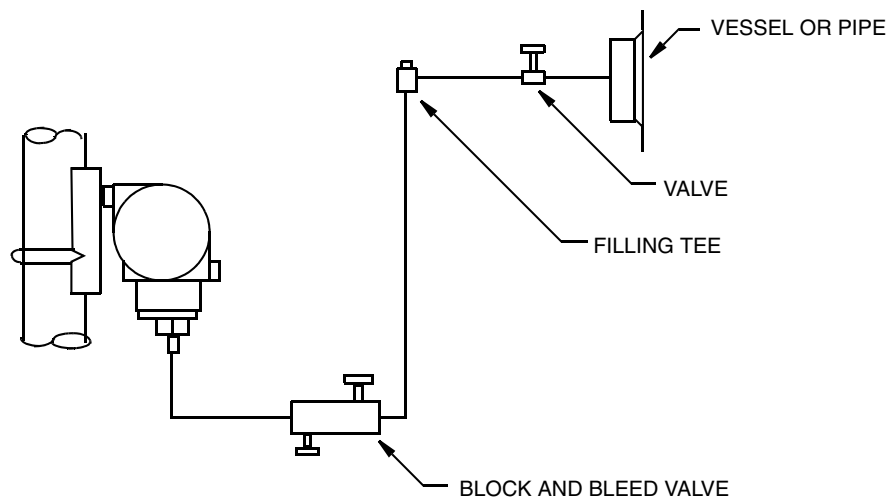


Figure 10. Hot Process Piping

Positioning the Housing

The transmitter housing (topworks) can be rotated up to one full turn in the counterclockwise direction when viewed from above for optimum access to adjustments, display, or conduit connections. Housings have either an anti-rotation screw or a retention clip that prevent the housing from being rotated beyond a safe depth of housing/sensor thread engagement.

! WARNING

If the electronics housing is removed for maintenance, it must be hand tightened to the bottom of the threads, but not over-tightened upon reassembly. See “Removing and Reinstalling a Housing Assembly” on page 55.

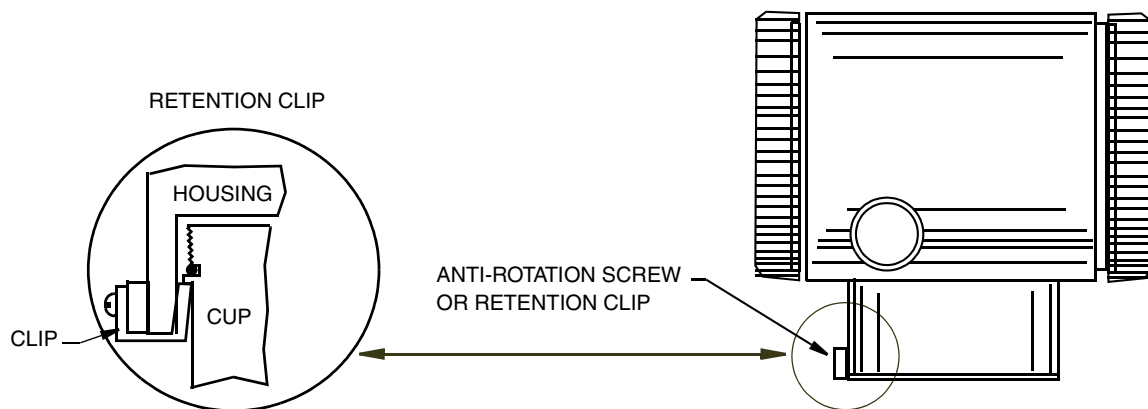


Figure 11. Housing Screw or Clip Location

Positioning the Display

The display (optional in some models) can be rotated within the housing to any of four positions at 90° increments. To do this, grasp the two tabs on the display and rotate it about 10° in a counterclockwise direction. Pull out the display. Ensure that the O-ring is fully seated in its groove in the display housing. Turn the display to the desired position, reinsert it in the electronics module, aligning the tabs on the sides of the assembly, and twist it in the clockwise direction.

! CAUTION

Do **not** turn the display more than 180° in any direction. Doing so could damage its connecting cable.

Setting the Write Protect Jumper

Your transmitter has write protection capability. This means that the external zero, local display, and remote communications can be prevented from writing to the electronics. Write protection is set by moving a jumper that is located in the electronics compartment behind the optional

display. To activate write protection, remove the display as described in the previous section, then remove the jumper or move it to the lower position as shown on the exposed label. Replace the display.

Cover Locks

Electronic housing cover locks, shown in Figure 12, are provided as standard with certain agency certifications and as part of the Custody Transfer Lock and Seal option. To lock the covers, unscrew the locking pin until approximately 6 mm (0.25 in) shows, lining up the hole in the pin with the hole in the housing. Insert the seal wire through the two holes, slide the seal onto the wire ends and crimp the seal.

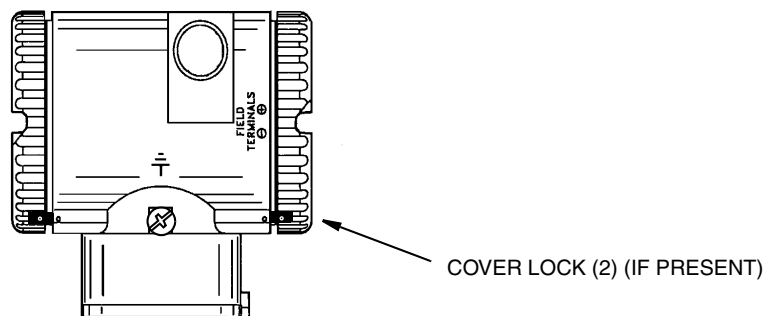


Figure 12. Cover Lock Location

Wiring

The installation and wiring of your transmitter must conform to local code requirements.

— **! WARNING** —

ATEX requires that when the equipment is intended to be used in an explosive atmosphere caused by the presence of combustible dust, cable entry devices and blanking elements shall provide a degree of ingress protection of at least IP6X. They shall be suitable for the conditions of use and correctly installed.

— **NOTE** —

Invensys recommends the use of transient/surge protection in installations prone to high levels of electrical transients and surges.

Accessing Transmitter Field Terminals

For access to the field terminals, thread the cover lock (if present) into the housing to clear the threaded cover and remove the cover from the field terminals compartment as shown in Figure 13. Note that the embossed letters **FIELD TERMINALS** identify the proper compartment.

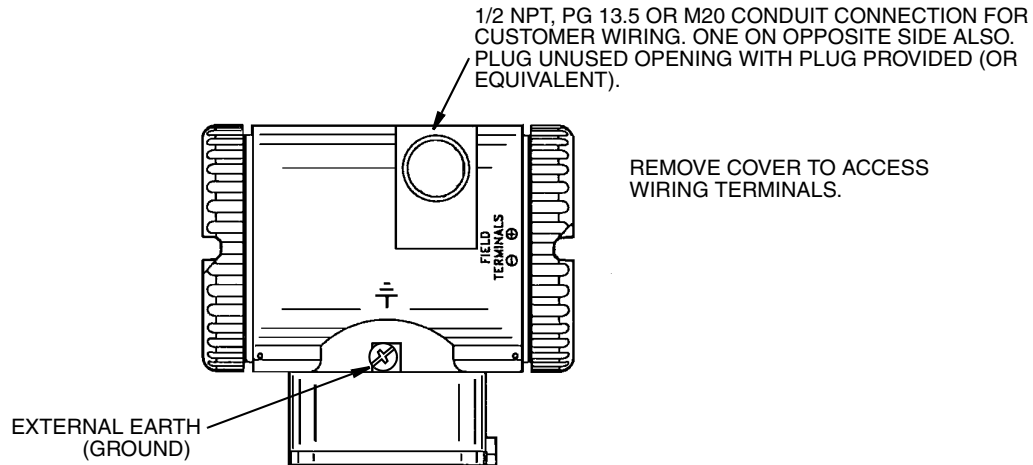


Figure 13. Accessing Field Terminals

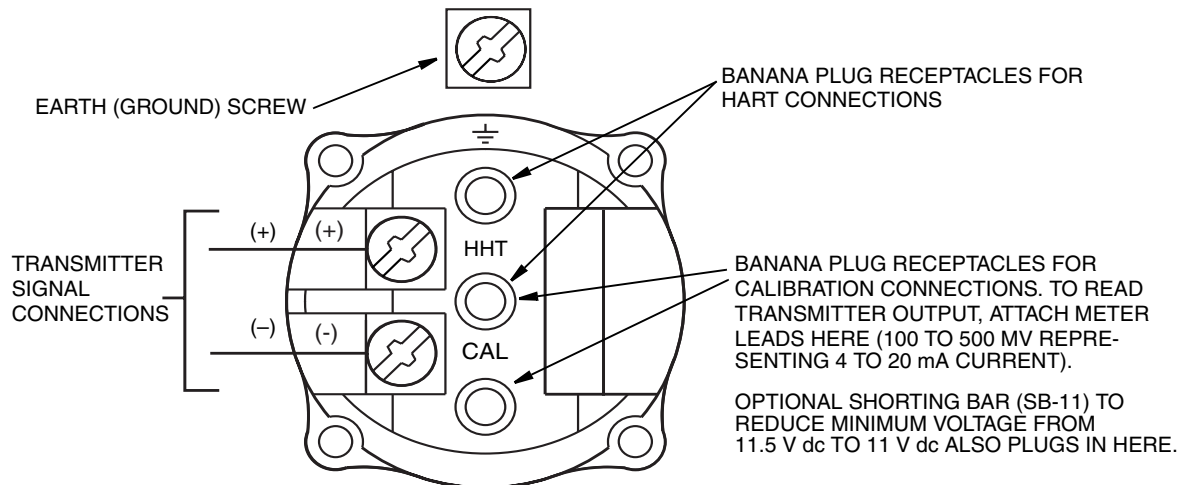


Figure 14. Identification of Field Terminals

Wiring the Transmitter to a Control Loop

When wiring the transmitter, the supply voltage and loop load must be within specified limits. The supply output load vs. voltage relationship is:

$$R_{MAX} = 47.5 (V - 11.5) \text{ and is shown in Figure 15.}$$

— **NOTE** —

The relationship when the optional shorting bar is used is:

$$R_{MAX} = 46.8 (V - 11).$$

Any combination of supply voltage and loop load resistance in the shaded area can be used. To determine the loop load resistance (transmitter output load), add the series resistance of each component in the loop, excluding the transmitter. The power supply must be capable of supplying 22 mA of loop current.

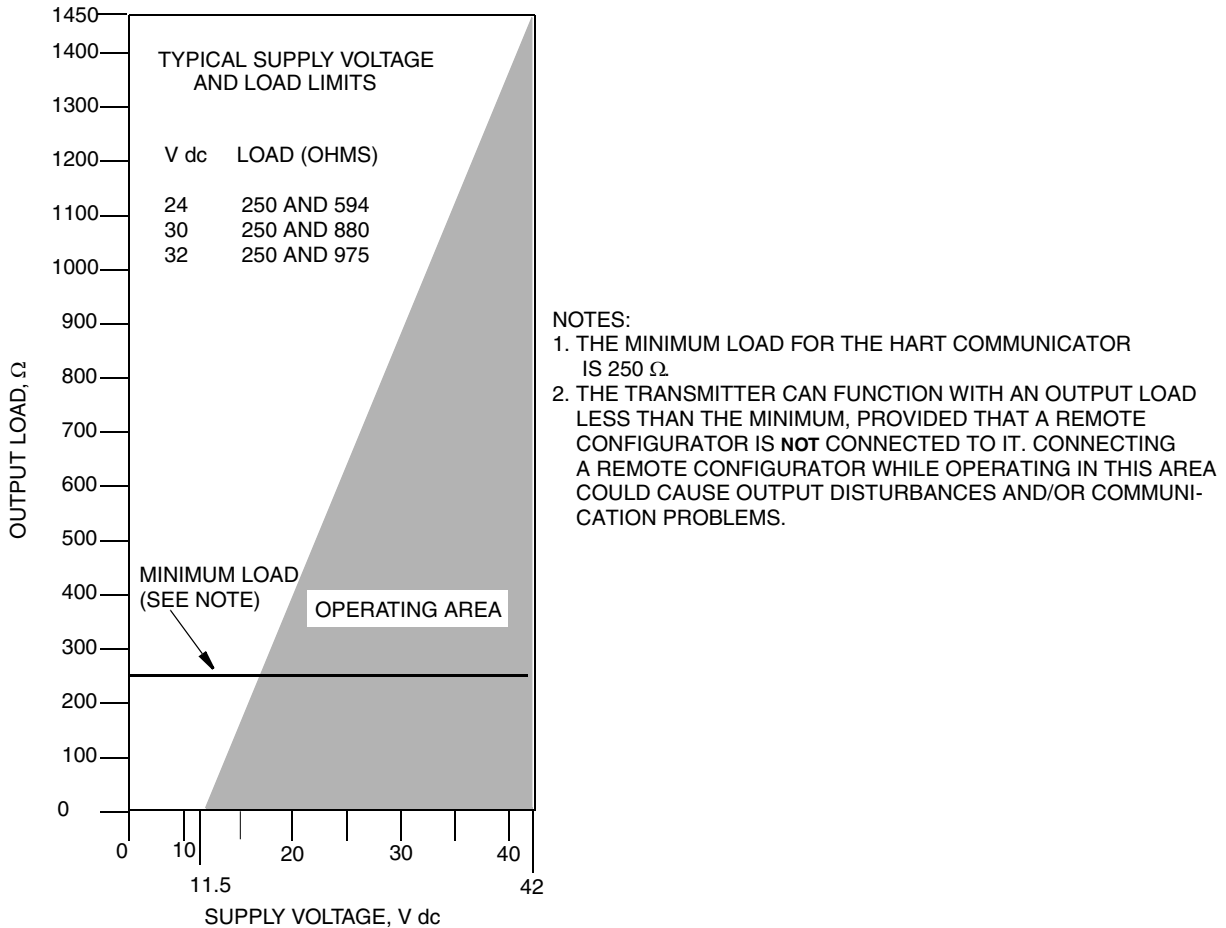


Figure 15. Supply Voltage and Loop Load

Examples:

1. For a loop load resistance of 880 Ω, the supply voltage can be any value from 30 to 42 V dc.
2. For a supply voltage of 24 V dc, the loop load resistance can be any value from 250 to 594 Ω (zero to 594 Ω without a HART Communicator connected to the transmitter).

To wire one or more transmitters to a power supply, proceed with the following steps.

1. Remove the cover from the transmitter field terminals compartment.
2. Run signal wires (0.50 mm² or 20 AWG, typical) through one of the transmitter conduit connections. Use twisted single pair to protect the 4 to 20 mA output and/or remote communications from electrical noise. Maximum recommended length for signal wires is:
 - ◆ 3050 m (10,000 ft) **using single pair cable** and adhering to requirements of HART physical layer implementation defined in HART Document HCF_SPEC-53. Use CN=1 when calculating max. lengths.
 - ◆ 1525 m (5000 ft) in a multidrop (15 devices maximum) mode. Screened (shielded) cable could be required in some locations.

— NOTE

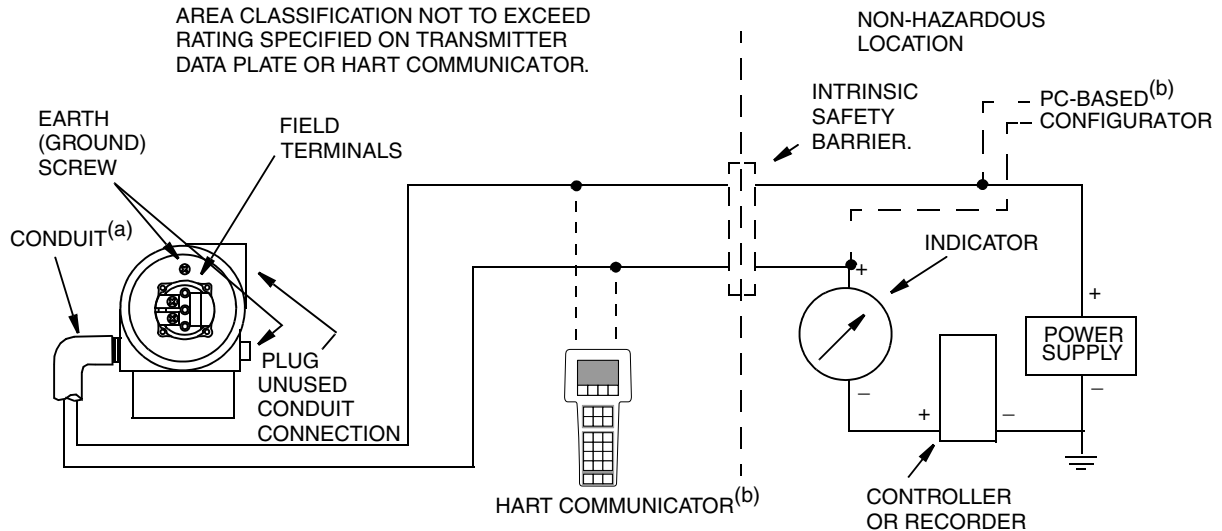
Do not run transmitter wires in same conduit as mains (ac power) wires.

3. If shielded cable is used, earth (ground) the shield at the power supply **only**. Do not ground the shield at the transmitter.
4. Plug unused conduit connection with the 1/2 NPT, PG 13.5 or M20 metal plug provided (or equivalent). To maintain specified explosionproof and dust-ignitionproof protection, plug must engage a **minimum** of five full threads for 1/2 NPT connections; seven full threads for M20 and PG 13.5 connections.
5. Connect an earth (ground) wire to the earth terminal in accordance with local practice.

— ! CAUTION

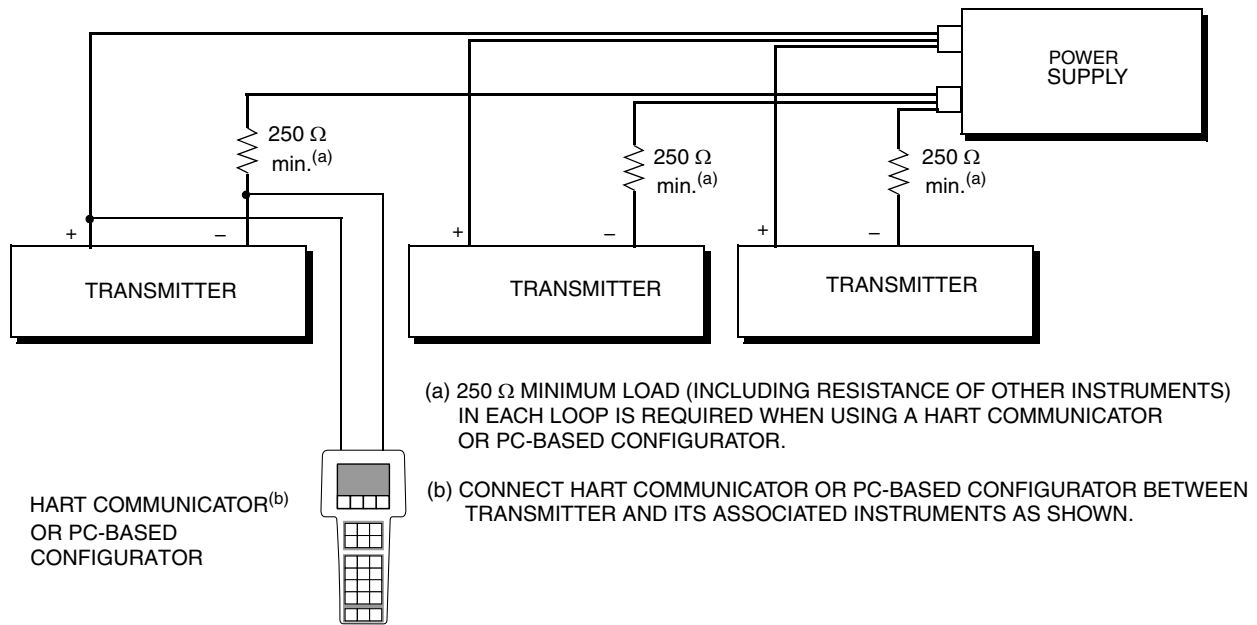
If the signal circuit must be earthed (grounded), it is preferable to do so at the negative terminal of the dc power supply. To avoid errors resulting from earth loops or the possibility of short-circuiting groups of instruments in a loop, there should be only one earth in a loop.

6. Connect the power supply and receiver loop wires to the “+” and “–” terminal connections.
7. Connect receivers (such as controllers, recorders, indicators) in series with power supply and transmitter as shown in Figure 16.
8. Reinstall the cover onto the housing by rotating it clockwise to seat the O-ring into the housing and then continue to hand tighten until the cover contacts the housing metal-to-metal. If cover locks are present, lock the cover per the procedure described in “Cover Locks” on page 21.
9. If wiring additional transmitters to the same power supply, repeat Steps 1 through 8 for each additional transmitter. The setup with multiple transmitters connected to a single power supply is shown in Figure 17.
10. A HART Communicator or PC-Based Configurator can be connected in the loop between the transmitter and the power supply as shown in Figures 16 and 17. Note that a minimum of 250 Ω must separate the power supply from the HART Communicator or PC-Based Configurator.



- (a) RUN CONDUIT DOWN TO AVOID MOISTURE BUILDUP IN TERMINALS COMPARTMENT.
- (b) THERE MUST BE AT LEAST 250 Ω TOTAL RESISTANCE BETWEEN THE HART COMMUNICATOR OR THE PC-BASED CONFIGURATOR AND THE POWER SUPPLY.

Figure 16. Loop Wiring Transmitters



- (a) 250 Ω MINIMUM LOAD (INCLUDING RESISTANCE OF OTHER INSTRUMENTS) IN EACH LOOP IS REQUIRED WHEN USING A HART COMMUNICATOR OR PC-BASED CONFIGURATOR.
- (b) CONNECT HART COMMUNICATOR OR PC-BASED CONFIGURATOR BETWEEN TRANSMITTER AND ITS ASSOCIATED INSTRUMENTS AS SHOWN.

Figure 17. Wiring Several Transmitters to a Common Power Supply

Multidrop Communication

“Multidropping” refers to the connection of several transmitters to a single communications transmission line. Communications between the host computer and the transmitters takes place digitally with the analog output of the transmitter deactivated. With the HART communications protocol, up to 15 transmitters can be connected on a single twisted pair of wires or over leased telephone lines.

The application of a multidrop installation requires consideration of the update rate necessary from each transmitter, the combination of transmitter models, and the length of the transmission line. Multidrop installations are not recommended where Intrinsic Safety is a requirement. Communication with the transmitters can be accomplished with any HART compatible modem and a host implementing the HART protocol. Each transmitter is identified by a unique address (1-15) and responds to the commands defined in the HART protocol.

Figure 18 shows a typical multidrop network. Do not use this figure as an installation diagram. Contact the HART Communications Foundation, (512) 794-0369, with specific requirements for multidrop applications.

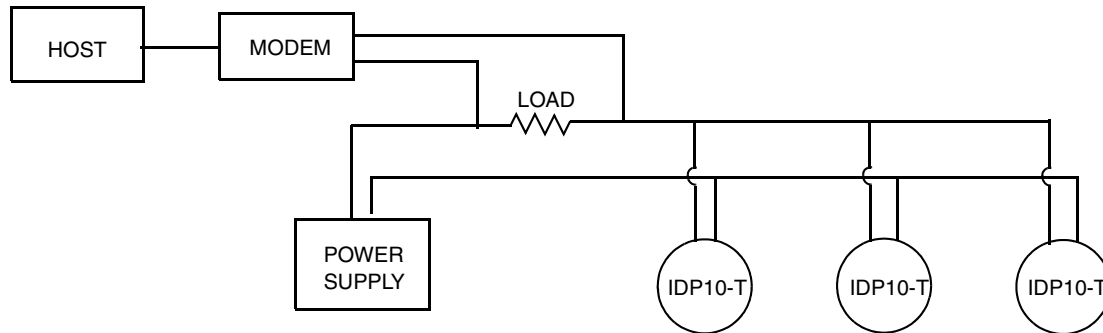


Figure 18. Typical Multidrop Network

The HART Communicator can operate, configure, and calibrate IASPT transmitters with HART communication protocol in the same way as it can in a standard point-to-point installation.

— **NOTE** —

IASPT transmitters with HART communication protocol are set to poll address 0 (**POLLADR 0**) at the factory, allowing them to operate in the standard point-to-point manner with a 4 to 20 mA output signal. To activate multidrop communication, the transmitter address must be changed to a number from 1 to 15. Each transmitter must be assigned a unique number on each multidrop network. This change deactivates the 4 to 20 mA analog output.

Connecting the Transmitter to an I/A Series System

The transmitter can also send its measurement to an I/A Series system as a digital signal via an FBM214/215. Wiring terminations at the transmitter are the same as described above. For other system wiring details, refer to the installation instructions provided with the I/A Series system.

3. Operation Via Local Display

A local display, as shown in Figure 19, has two lines of information. The upper line is a 5-digit numeric display (4-digit when a minus sign is needed); the lower line is a 7-digit alphanumeric display. The display provides local indication of measurement information. The primary (M1) measurement is normally displayed. To view the secondary (M2) measurement, press the **Enter** button while in normal operating mode. Press the **Next** or **Enter** button to return to the primary measurement. If left in M2 display, an M2 message blinks in the lower right of the display. If power to the transmitter is interrupted, the display reverts to the M1 display.

The display also provides a means for performing calibration and configuration, viewing the database, and testing the display via the 2-button keypad. You can access these operations by means of a multi-level menu system. Entry to the Mode Select menu is made (from normal operating mode) by pressing the **Next** button. You can exit this menu, restore your prior calibration or configuration, and return to the normal operating mode at any time by going to **Cancel** and pressing the **Enter** button.

The following items can be selected from this menu: Calibration (**CALIB**), Configuration (**CONFIG**), Viewing the database (**VIEW DB**), and Testing the display (**TST DSP**). The top level structure diagram is shown in Figure 20.

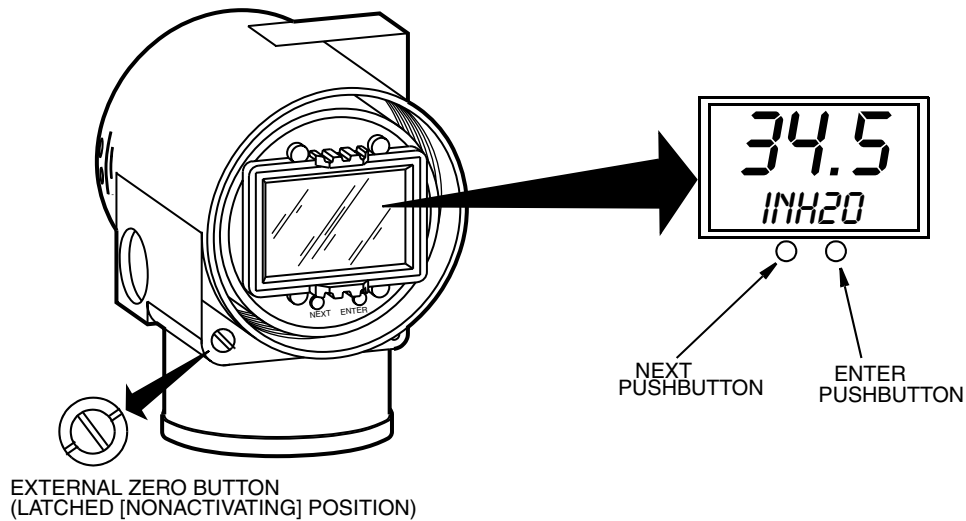


Figure 19. Local Display Module

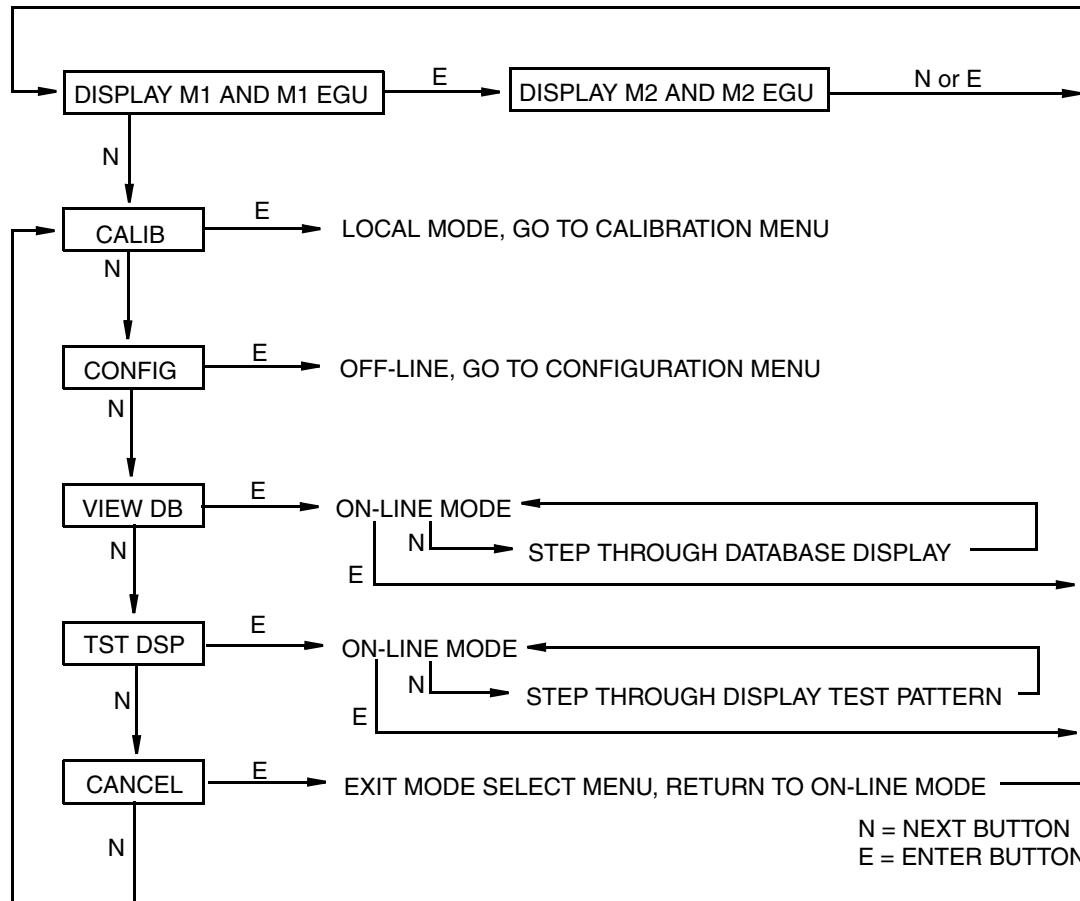


Figure 20. Top Level Structure Diagram

Entering Numerical Values

The general procedure for entering numerical values in Calibration and Configuration is as follows:

1. At the appropriate prompt, press the **Enter** button. The display shows the last (or default) value with the first digit flashing.
2. Use the **Next** button to select the desired first digit, then press the **Enter** button. Your selection is entered and the second digit flashes.
3. Repeat Step 2 until you have created your new value. If the number has less than five characters, use leading or trailing zeros for the remaining spaces. When you have configured the fifth space, the display prompts you to place the decimal point.
4. Move the decimal point with the **Next** button until it is where you want it and press the **Enter** button.

— NOTE

1. The decimal point may not be placed directly after the first digit. For example, you can not enter a value as 1.2300; you must enter it as 01.230.
 2. The decimal position is identified by flashing except at the position after the fifth digit. At that position (representing a whole number), the decimal point is assumed.
-

5. The display advances to the next menu item.

Viewing the Database

You can access the View Database mode by the multi-level menu system described above. Entry to the Mode Select menu is made (from normal operating mode) by pressing the **Next** button. The display reads **CALIB**, the first item on the menu. Press the **Next** button twice to get to the third item on the menu, **VIEW DB**. Acknowledge your choice of this selection by pressing the **Enter** button. The display shows the first item in the database. You can step through the database display by repeated use of the **Next** button. You can abort this procedure at any time by pressing the **Enter** button.

Viewing the Pressure Range

The values of **M1LRV** and **M1 URV** can be viewed in **VIEW DB** as described above. They can also be viewed in the **RERANGE** function in Calibration mode.

Testing the Display

You can access the Test Display mode by the same multi-level menu system that was used to enter Calibration, Configuration, and View Database mode. Entry to the Mode Select menu is made (from normal operating mode) by pressing the **Next** button. The display reads **CALIB**, the first item on the menu. Press the **Next** button three times to get to the fourth item on the menu, **TST DSP**. Acknowledge your choice of this selection by pressing the **Enter** button. The display shows the first test segment pattern. You can step through the five patterns by repeated use of the **Next** button. You can abort the test at any time by pressing the **Enter** button. The five patterns are shown in Figure 21.

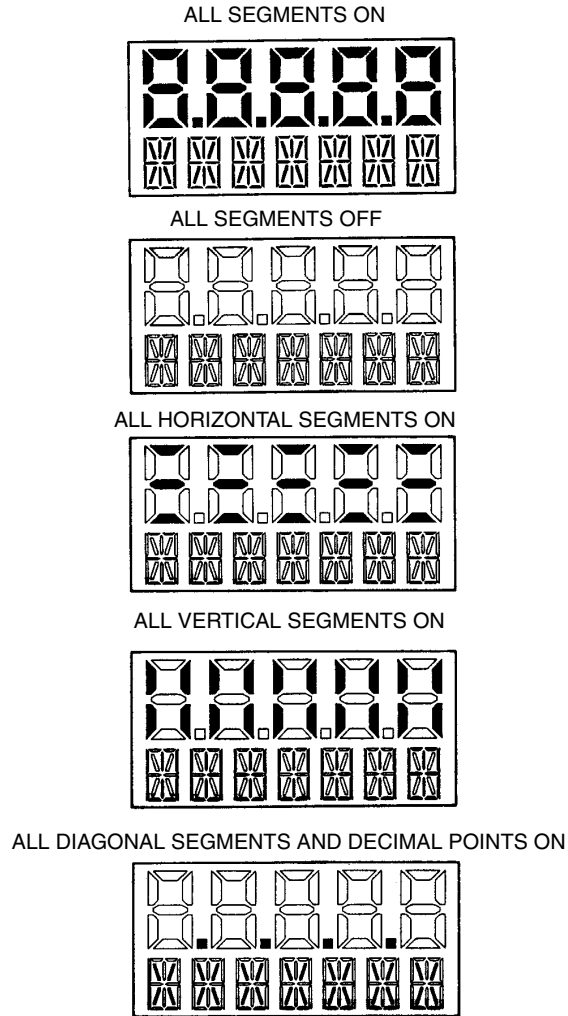


Figure 21. Display Test Segment Patterns

Error Messages

Table 4. Operation Error Messages

| Parameter | Condition Tested | Error Message | Action |
|------------------|---------------------------|---------------|---|
| Normal Operation | Write Protection Enabled | WR PROT | Displays periodically to notify user that unit is in Write Protect. |
| | Any non-On-line Condition | OFFLINE | Notifies user of a non-On-line condition. |
| Startup | Database OK or corrupted | INITERR | User should perform SET GDB procedure. See “SET GDB:” on page 49. |

4. Calibration

NOTE

1. For best results in applications where high accuracy is required, rezero the transmitter output once it has stabilized at the final operating temperature.
 2. Zero shifts resulting from position effects and/or static pressure effects can be eliminated by rezeroing the transmitter output.
 3. After calibrating transmitters operating with a 4 to 20 mA (or 1 to 5 V dc) output signal, check the underrange and overrange output values to ensure that they extend beyond 4 and 20 mA (or 1 and 5 V dc) respectively.
-

General Calibration Notes

1. Each transmitter is factory characterized over its full rated pressure range. One benefit of this process is that every transmitter can measure any applied pressure within its range limits regardless of the calibrated range. The applied pressure is measured and converted into an internal digital value of pressure. This digital value of pressure is always available whether the transmitter is calibrated or not. Calibration assures that the transmitter rated accuracy is achieved over the calibrated range.
2. The internal digital value of pressure can be displayed on the optional local display, transmitted digitally, and converted to a 4 to 20 mA analog output signal.
3. Each transmitter is factory calibrated to either a specified or a default calibrated range. This calibration optimizes the accuracy of the internal digital value of pressure over that range. If no range is specified, the default range is zero to the sensor upper range limit (URL).
4. The transmitter database has configurable values for both lower range value (LRV) and upper range value (URV). These values are used for two functions.
 - a. Defining the Calibrated Range When Using Local Pushbuttons for Calibration:
 - ◆ When either **CAL LRV** or **CAL URV** is initiated from the local pushbuttons, the transmitter expects that the pressure applied at the time the button is pressed is equal to the LRV or URV value respectively.
 - ◆ This function trims the internal digital value of pressure; that is, it performs a calibration based on the application of accurate pressures equal to the values entered for LRV and URV in the transmitter database.
 - ◆ This function also sets the 4 and 20 mA output points; that is, the 4 and 20 mA points correspond to the values of LRV and URV in the database.
 - ◆ The value of LRV can be larger than the value of URV.
 - b. Reranging Without the Application of Pressure:
 - ◆ Since the transmitter continually determines an internal digital value of the measured pressure from the lower range limit (LRL) to the upper range limit

- (URL), the 4 and 20 mA output points can be assigned to any pressure values (within the span and range limits) without application of pressure.
- ◆ The reranging function is accomplished by entering new database values for LRV and URV.
 - ◆ Reranging does not affect the calibration of the transmitter; that is, it does not affect the optimization of the internal digital value of pressure over a specific calibrated range.
 - ◆ If the reranged LRV and URV are not within the calibrated range, the measured values may not be as accurate as when they are within the calibrated range.
5. When the optional local display is used, the internal digital value of pressure is sent directly to the indicator.
- ◆ The display can show any measured pressure in selected units regardless of the calibrated range and the values of LRV and URV (within the limits of the transmitter and display).
 - ◆ If the measured pressure is outside the range established by the LRV and URV values in the database, the display shows the measurement but also continually blinks to indicate that the measurement is out of range. The mA current signal is saturated at either the low or high overrange limit respectively but the display continually shows the pressure.
6. When configured for 4 to 20 mA output, the internal digital value of pressure is converted to an analog current signal.
- ◆ The transmitter sets the output at 4 mA for the LRV and 20 mA for the URV.
 - ◆ There is an independent trim on the digital-to-analog conversion stage. This trim allows for slight adjustment of the 4 and 20 mA outputs. This compensates for any slight difference that exists between the transmitter mA output and an external reference device which is measuring the current.
 - ◆ The mA trim does not affect the calibration or the reranging of the transmitter and does not affect the internal digital value of pressure or the transmission or display of measured pressure.
 - ◆ The mA trim can be done with or without pressure applied to the transmitter.
7. Zeroing from the local display does not affect the span.

When the transmitter is zeroed to compensate for installed position effect, the transmitter can have either LRV pressure applied (**CAL LRV**) or zero pressure applied (**CAL ATO**). If the range is zero-based, either method produces the same result. However, if the range is not zero-based, it is advantageous to have both methods available.

For example, consider a pressure transmitter having a range of 50 to 100 psig. If it is not feasible to vent the transmitter to atmosphere for zeroing, it can be zeroed while the LRV pressure of 50 psi is applied by using the **CAL LRV** function. On the other hand, if the transmitter has been installed but there is no pressure in the process line yet, it can be zeroed while open to atmosphere by using the **CAL ATO** function.

- a. Zeroing with LRV Pressure Applied (**CAL LRV**):
 - ◆ Before using this zeroing function, apply a pressure to the transmitter equal to the value of LRV stored in the transmitter database.
 - ◆ When you zero the transmitter, the internal digital value of the pressure is trimmed to be equal to the value of LRV stored in the database and the mA output set to 4 mA.
 - ◆ If zeroing is done when the applied pressure is different from the LRV pressure value in the database, the internal digital value of pressure is biased by the difference in the values but the output is still set at 4 mA.
 - ◆ The **CAL LRV** and **CAL URV** function should be used when calibrating a transmitter for a specific range with known input pressures applied for the LRV and URV.
- b. Zeroing with Zero Pressure Applied (**CAL AT0**):
 - ◆ Make sure that the applied pressure is at zero. This means venting the transmitter to atmosphere.
 - ◆ When you zero the transmitter, the internal digital value of the pressure is trimmed to be equal to zero and the mA output set to an appropriate value such that the mA output is a normal 4 mA when the LRV pressure is applied later.

Calibration Setup

The following sections show setups for field or bench calibration. Use test equipment that is at least three times as accurate as the desired accuracy of the transmitter.

— **NOTE** —

It is not necessary to set up calibration equipment to rerange the transmitter to a different range. The transmitter can be accurately reranged by simply changing the lower range value and the upper range value, which are stored in the transmitter database.

Setup of Electronic Equipment

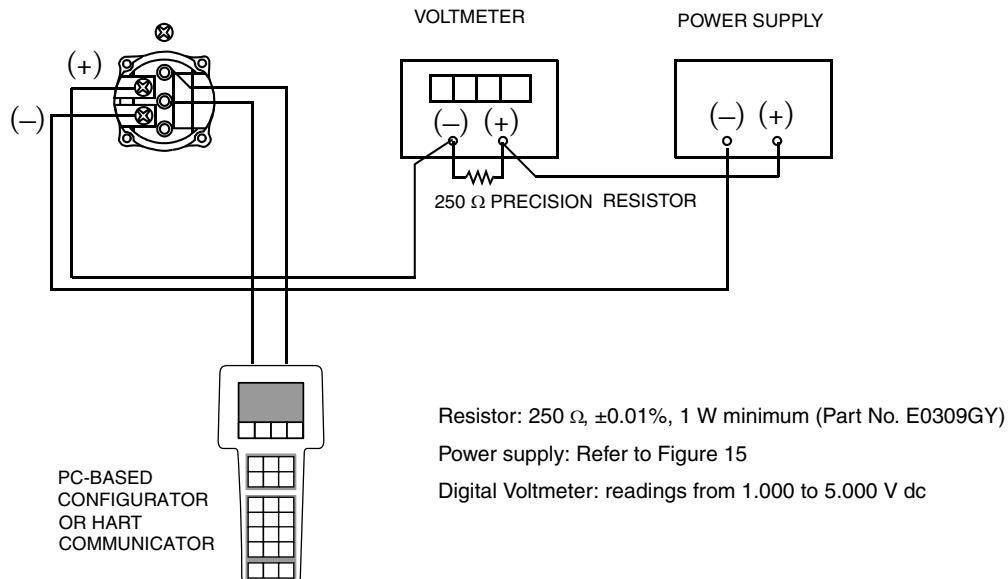
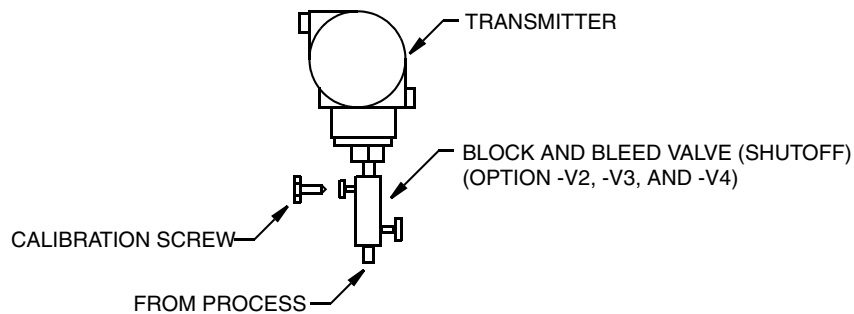


Figure 22. 4 to 20 mA Output Calibration Setup of Electronic Equipment

Field Calibration Setup

Field calibration is performed without disconnecting the process piping. This is only possible if the transmitter is piped as shown in Figure 23.



NOTE: Block and Bleed Valve Maximum Pressure
 40 MPa (6000 psi at 38°C (100°F))
 25 MPa (4000 psi at 250°C (400°F))
 Calibration Screw Maximum Pressure
 0.7 MPa (100 psi with Poly-Flo Fitting (F0101ES))

Figure 23. Transmitter Piping

If the transmitter is to be removed from the process for calibration, refer to “Bench Calibration Setup” below.

An adjustable air supply and a pressure measuring device are required. For example, a dead weight tester or an adjustable clean air supply and pressure gauge can be used.

Bench Calibration Setup

The bench calibration setup requires disconnecting the process piping. For calibration setup without disconnecting the process piping, refer to “Field Calibration Setup” above.

The bench calibration setup is shown in Figure 24. If calibrating the output signal, also connect equipment as shown in Figure 22.

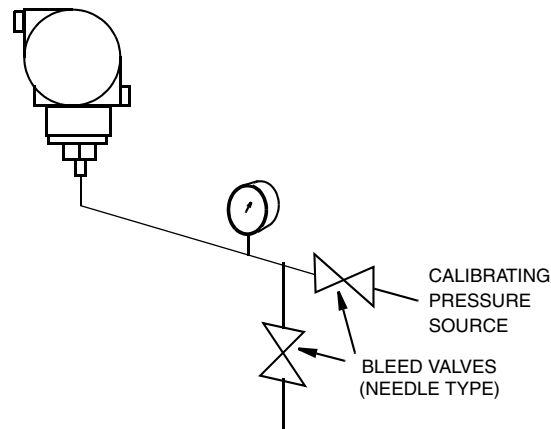


Figure 24. Bench Calibration Setup

Calibration Using a PC50

To calibrate the transmitter using a PC50 Configurator, follow the procedure in MI 020-501 and MI 020-520.

Calibration Using a HART Communicator

To calibrate the transmitter using a HART Communicator, follow the procedure in MI 020-366.

Calibration Using the Optional Local Display

To access the Calibration mode (from normal operating mode), press the **Next** button. The display reads **CALIB**, the first item on the menu. Acknowledge your choice of this selection by pressing the **Enter** button. The display shows the first item in the Calibration menu.

— **NOTE** —

1. During calibration, a single change could affect several parameters. For this reason, if an entry is entered in error, re-examine the entire database or use the **Cancel** feature to restore the transmitter to its starting configuration and begin again.
 2. During adjustment of 4 and 20 mA in the Calibration menu, the milliamper output does not reflect live measurement values.
-

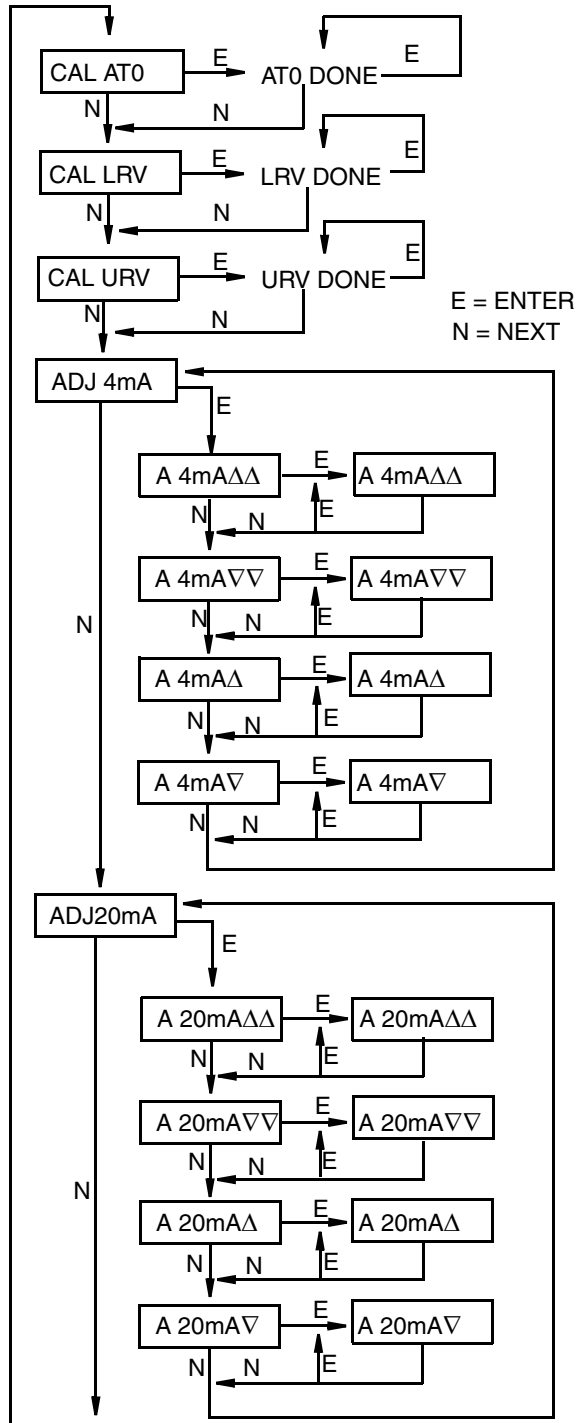
Table 5. Calibration Menu

| Item | Description |
|--|---|
| CAL AT0 | Calibrate at zero pressure. |
| CAL LRV | Calibrate with pressure at 0% of transmitter range (LRV). |
| CAL URV | Calibrate with pressure at 100% of transmitter range (URV). |
| ADJ 4mA | Adjust nominal 4 mA output. |
| ADJ20mA | Adjust nominal 20 mA output. |
| RERANGE | Adjust primary upper and lower range values. |
| CALDATE | Enter the calibration date. |
| ADJ 4mA causes the following four submenus. | |
| A 4mAΔΔ | Increase 4 mA output by large step. |
| A 4mA∇∇ | Decrease 4 mA output by large step. |
| A 4mAΔ | Increase 4 mA output by small step. |
| A 4mA∇ | Decrease 4 mA output by small step. |
| ADJ 20mA causes the following four submenus. | |
| A 20mAΔΔ | Increase 20 mA output by large step. |
| A 20mA∇∇ | Decrease 20 mA output by large step. |
| A 20mAΔ | Increase 20 mA output by small step. |
| A 20mA∇ | Decrease 20 mA output by small step. |
| RERANGE causes the following two submenus. | |
| M1 URV | Adjust upper range value. |
| M1 LRV | Adjust lower range value. |

— NOTE —

It is not necessary to use the **ADJ4mA** or **ADJ20mA** menu selections unless there is a plant requirement to make the 4 and 20 mA output values exactly match readings on certain plant calibration equipment and the **CAL LRV** and **CAL URV** operations done result in a small but unacceptable difference between the transmitter mA output and the test equipment mA readout values.

Proceed to calibrate your transmitter by using the **Next** key to select your item and the **Enter** key to specify your selection per the following two figures. At any point in the calibration you can **Cancel**, restore your prior calibration and return to the on-line mode or **Save** your new calibration.



RERANGE
(continued on next figure)

CAL AT0: To set or reset the zero point at zero pressure, apply zero pressure to the transmitter and, at display of **CAL AT0**, press **Enter**. This can be done whether LRV is zero or not. Completion is indicated by the display **AT0 Done**.

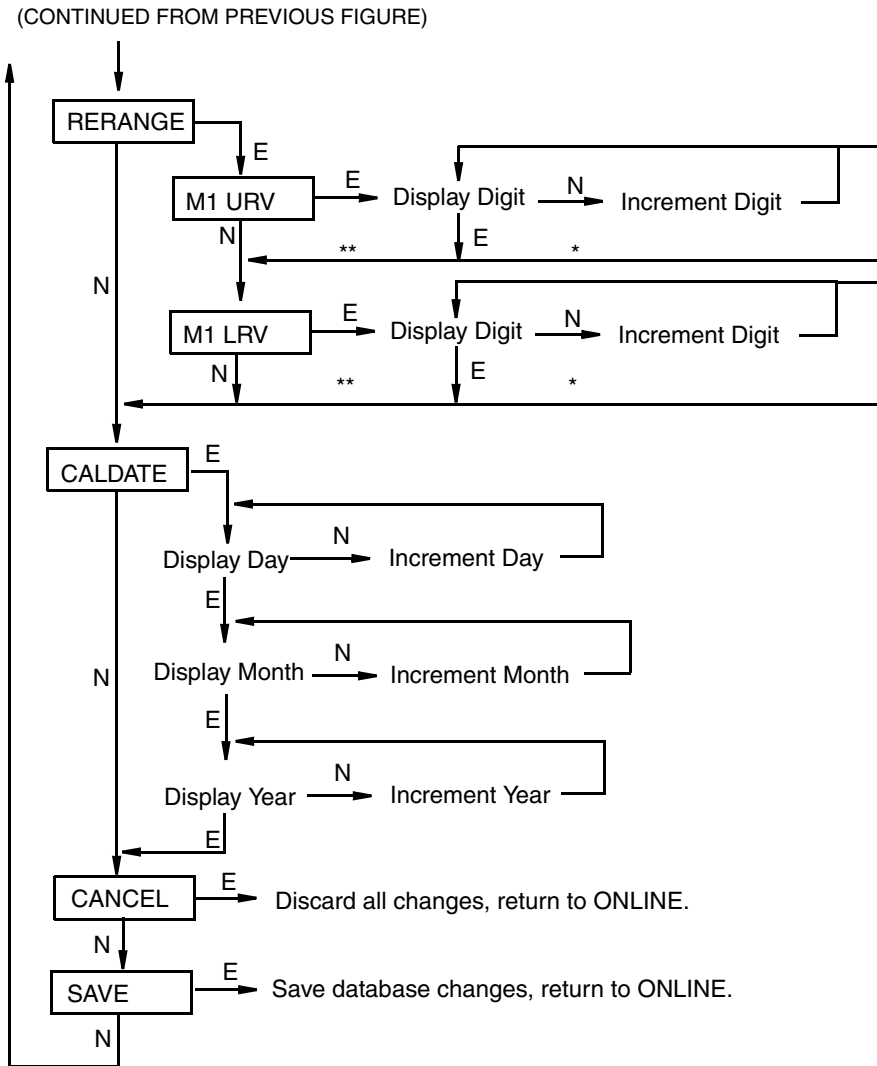
CAL LRV: To set or reset 0% of range input, apply pressure to the transmitter equal to the lower range value (LRV) in the transmitter database and, at display of **CAL LRV**, press **Enter**. Completion is indicated by the display **LRV Done**.

CAL URV: To set or reset 100% of range input, apply pressure to the transmitter equal to the upper range value (URV) in the transmitter database and, at display of **CAL URV**, press **Enter**. Completion is indicated by the display **URV Done**.

ADJ4mA: If you configured your transmitter operating mode as 4 to 20 mA, you can adjust the 4 mA output by going to **ADJ4mA** using the **Next** button and press **Enter**. This menu item is bypassed if you configured your transmitter operating mode as digital.

To increase the 4 mA output by a large (0.025 mA) step, press **Enter** at the display **A 4mAΔΔ**. To decrease it by a large step, go to the display **A 4mA∇∇** by pressing the **Next** button and then **Enter**. To increase it by a

Figure 25. Calibration Structure Diagram



*If character is not the last position on the display line, advances to next character.

**If character is the last position on the display line, advances to next menu item.

NOTE: Commentary about this diagram immediately follows.

Figure 26. Calibration Structure Diagram (Continued)

Commentary on Figure 26

RERANGE: To adjust 100% and 0% range values, go to **Rerange** with the **Next** button and press **Enter**. You can then adjust **M1 URV** and/or **M1 LRV** in the following two submenus.

M1 URV: To edit the upper range value, press **Enter** at the prompt **M1 URV**.

M1 LRV: Similar to **M1URV** immediately above.

CALDATE: This is not a required entry but can be used for recordkeeping or plant maintenance purposes. To edit the calibration date, go to **CALDATE** with the **Next** button and press **Enter**. You then can change the day, month, and year. The display shows the last date with the day

flashing. Use the **Next** button to step through the menu of digits to select the desired day, then press **Enter**. Repeat this process for the month and year.

Zero Adjustment Using External Zero Button

An external zero adjustment mechanism in the electronics housing allows local rezeroing of the transmitter output without removing the electronics compartment cover. The mechanism is magnetically activated through the housing wall to prevent moisture from entering the enclosure. Zeroing is accomplished when the external zero button is depressed.

To use this feature:

1. Unlatch the external zero button by turning it 90° in a counterclockwise direction so that the screwdriver slot lines up with the two holes in the face of the adjacent part. Do **not** push the button in with the screwdriver while doing this.
2. With the applied process pressure (LRV) at the desired value, press the button. The zero output of 4 mA is set at this pressure. If the transmitter contains the optional display, the display indicates **ZEROED**. Other possible messages are: **DISABLD** if **EX ZERO** is configured **EXZ DIS**, **WAIT20S** if the transmitter has just been powered or a rezeroing has just been accomplished, and **IGNORED** if the transmitter is not in the on-line mode.

— NOTE

For the optional display and the digitally transmitted measurement to be correct, the applied pressure must be equal to the value stored in the database for LRV. See “General Calibration Notes” on page 31.

3. If additional rezeroing is required after Steps 1 and 2 have been accomplished, wait 20 seconds and repeat Step 2.
4. Relatch the external zero button by turning it 90° in a clockwise direction to prevent accidental pressing of the button. Do **not** push the button in with the screwdriver while doing this.

Error Messages

Table 6. Calibration Error Messages

| Parameter | Condition Tested | Error Message | User Action |
|---------------------|------------------------------|---------------|---|
| Password Protection | Password | BAD PWD | Bad password entered, use another. |
| Write Protection | Write protection enabled | REJECT | Displays when user attempts an action that is write protected. |
| ZERO | Internal offset too large | BADZERO | Check applied pressure, configured M1 LRV and configured M1 EOFF . |
| SPAN | Slope too large or too small | BADSPAN | Check applied pressure, configured M1 LRV and configured M1 EFAC . |
| M1 URV | M1URV > max pressure in EGU | URV>FMX | Entered pressure is greater than maximum rated pressure of transmitter. Check entry. Verify EGUs. |
| | M1URV < min pressure in EGU | URV<FMN | Entered pressure is less than minimum rated pressure of transmitter. Check entry. Verify EGUs. |
| | M1 URV = M1 LRV | LRV=URV | Cannot set span to 0. Check entry. Check M1 LRV . |
| | M1 turndown exceeds limit | BADTDWN | Check entry. Check M1 LRV . |
| M1 LRV | M1LRV > max pressure in EGU | LRV>FMX | Entered pressure is greater than maximum rated pressure of transmitter. Check entry. Verify EGUs. |
| | M1LRV < min pressure in EGU | LRV<FMN | Entered pressure is less than minimum rated pressure of transmitter. Check entry. Verify EGUs. |
| | M1 URV = M1 LRV | LRV=URV | Cannot set span to 0. check entry. Check M1 URV . |
| | M1 turndown exceeds limit | BADTDWN | Check entry. Check M1 URV . |

5. Configuration

Configurable Parameters

The following table lists all the configurable parameters and the factory default for the IGP25-T, and IGP50-T Transmitters. The factory default values have been customized if the transmitter was ordered with optional feature -C2. The table also shows which parameters are configurable with the integral vs. remote configurators.

Table 7. Configurable Parameters

| Parameter | Capability | Factory Default | Configurable with | | Application Requirement |
|----------------------------|---|---|-------------------|----------------|-------------------------|
| | | | Integ. Indic. | Remote Config. | |
| Descriptors | | | | | |
| Tag Number | 8 characters max | Tag Number | No | Yes | |
| Descriptor | 16 characters max | Tag Name | No | Yes | |
| Message | 32 characters max | Inst Location | No | Yes | |
| Input | | | | | |
| Calibrated Range | LRV to URV in units listed in (a) below | See (b) below when not specified per S.O. | Yes | Yes | |
| Output | | | | | |
| Meas. #1 Output | 4 to 20 mA or Fixed Current. Specify Poll Address (1-15) for Fixed Current. | 4 to 20 mA | Yes | Yes | |
| Meas. #1 Mode | Linear | Linear | Yes | Yes | |
| Meas #1 EGUs | Select from units listed in (a) below. | Same as Calibrated Range | Yes | Yes | |
| Meas. #2 Mode | Linear | Linear | Yes | Yes | |
| Meas #2 EGUs | If linear, select from units listed in (a) below | Same as Calibrated Range | Yes | Yes | |
| Temp. Sensor Fail Strategy | Normal oper or fail-safe | Fail-safe | Yes | | |
| Fail-safe | High or Low | High | Yes | Yes | |
| External Zero | Enabled or Disabled | Enabled | Yes | Yes | |
| Damping | 0 to 32 seconds | None | Yes | Yes | |
| Poll Address | 0 - 15 | 0 | Yes | Yes | |
| LCD Indicator (c) | Meas #1 EGU or % Lin | Meas #1 EGU | Yes | No | |

Table 7. Configurable Parameters (Continued)

| Parameter | Capability | Factory Default | Configurable with | | Application Requirement |
|-----------|------------|-----------------|-------------------|----------------|-------------------------|
| | | | Integ. Indic. | Remote Config. | |

(a) psi, inHg, ftH₂O, inH₂O, atm, bar, mbar, MPa, Pa, kPa, kg/cm², g/cm², mmHg, torr, mmH₂O

(b) Span Code D: 0 to 200 psi; Span Code E: 0 to 2000 psi

(c) Measurement #2 can be displayed at any time by pressing the **Enter** button regardless of the local display configuration. This reverts to Measurement #1 or % Lin (as configured) when power is cycled off and on.

Configuration Using a PC50

To configure the transmitter using a PC50 Configurator, follow the procedure in MI 020-501 and MI 020-520.

Configuration Using a HART Communicator

To configure the transmitter using a HART Communicator, follow the procedure in MI 020-366.

Configuration Using the Optional Local Display

You can access the Configuration mode by the same multi-level menu system that was used to enter Calibration mode. Entry to the Mode Select menu is made (from normal operating mode) by pressing the **Next** button. The display reads **CALIB**, the first item on the menu. Press the **Next** button again to get to the second item on the menu, **CONFIG**. Acknowledge your choice of this selection by pressing the **Enter** button. The display shows the first item in the Configuration menu. You can then configure items shown in the following table. The standard factory default configuration is also given in this table.

The standard factory default configuration is not used if custom configuration option -C2 has been specified. Option -C2 is a full factory configuration of all parameters to the user's specifications.

— NOTE —

1. You can configure most parameters using the local display. However, for more complete configuration capability, use a HART Communicator or PC-Based configurator.
 2. During configuration, a single change can affect several parameters. For this reason, if an entry is entered in error, re-examine the entire database or use the **Cancel** feature to restore the transmitter to its starting configuration and begin again.
-

Table 8. Configuration Menu

| Item | Description | Initial Factory Configuration |
|------------------------|--|-------------------------------|
| POLLADR | Poll Address: 0 - 15 | 0 |
| EX ZERO ^(a) | External Zero: enable or disable | Enable |
| S2 FAIL | Temperature Sensor Failure Strategy: S2FATAL or S2NOFTL | S2FATAL |
| OUT DIR | 4 to 20 mA Output: forward or reverse | Forward |
| OUTFAIL | 4 to 20 mA Output: fail mode output - low or high | High |
| OFFL MA | 4 to 20 mA Output in offline mode - last or user set | USER MA |
| DAMPING | Damping: none, 1/4, 1/2, 1, 2, 4, 8, 16, or 32 seconds | None |
| M1 MODE | Output: linear or type of square root ^(b) | Linear |
| M1DISP | Local Indicator Display in linear mode: in percent or engineering units | M1EGU |
| M1 EGU | User-Defined Engineering Units | inH ₂ O or psi |
| RERANGE | Adjustment of 100% and 0% range limits | - - - |
| M1 URV | Primary Upper Range Value | URL |
| M1 LRV | Primary Lower Range Value | 0 |
| M2 MODE | Output: linear or type of square root ^(b) | Linear |
| M2 EGU | User-Defined Engineering Units | Same as M1 EGU |
| DISPLAY | Show 1, Show 2, or Toggle (between M1 and M2) | Show 1 |
| CALDATE | Calibration Date | - - - |
| ENA PWD | Enable password; no password, configuration only, or configuration and calibration | NO PWD |
| CFG PWD | User set configuration password (six characters) | - - - |
| CAL PWD | User set calibration password (six characters) | - - - |
| SET GDB | Rewrite all calibration and configuration values with default values | - - - |

(a) Applies only if transmitter contains External Zero option.

(b) Square root selection is not applicable to gauge pressure measurement.

Proceed to configure your transmitter by using the **Next** button to select your item and the **Enter** button to specify your selection per the following figures. At any point in the configuration you can **Cancel** your changes and return to the on-line mode, or **Save** your changes.

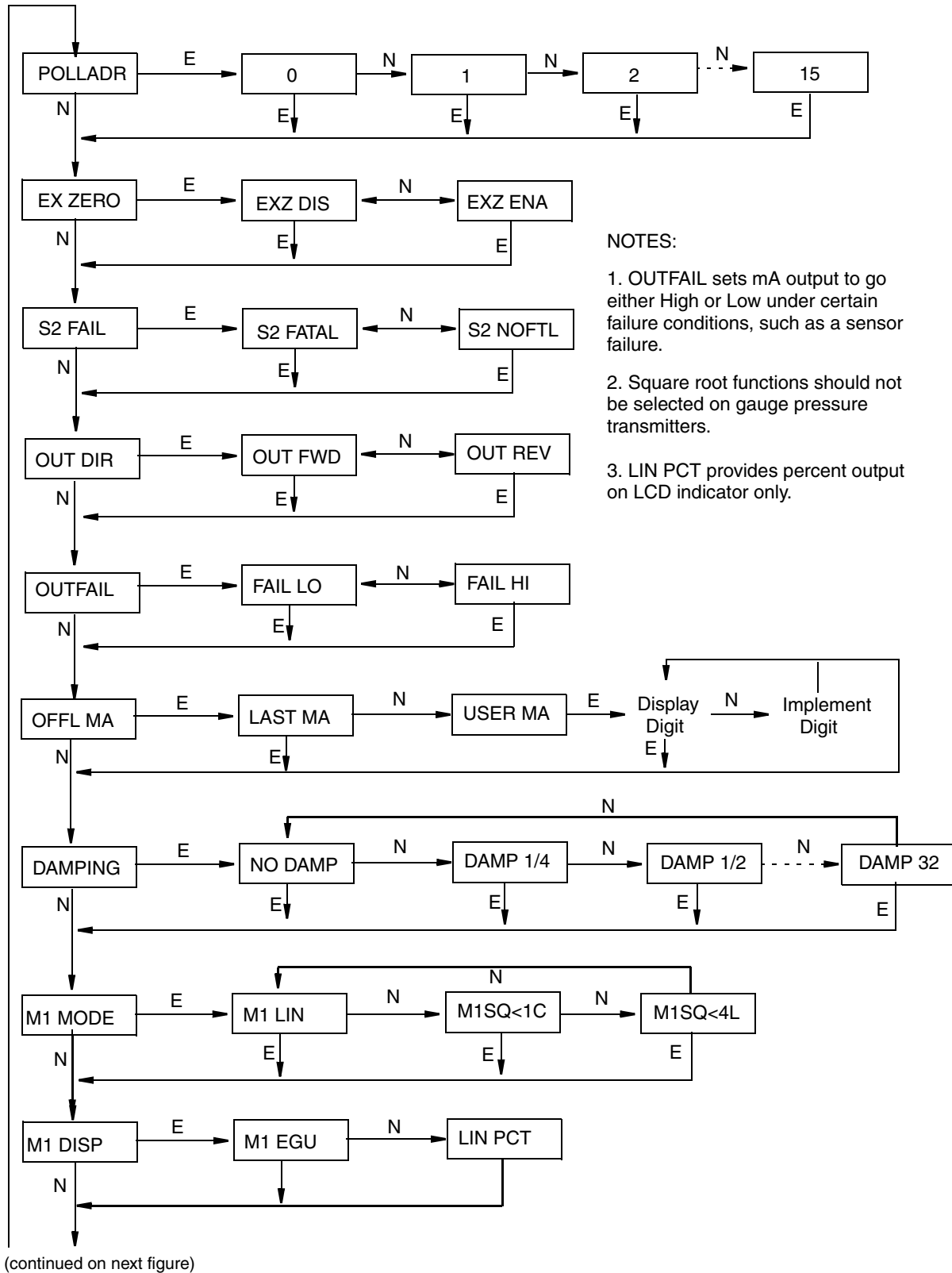
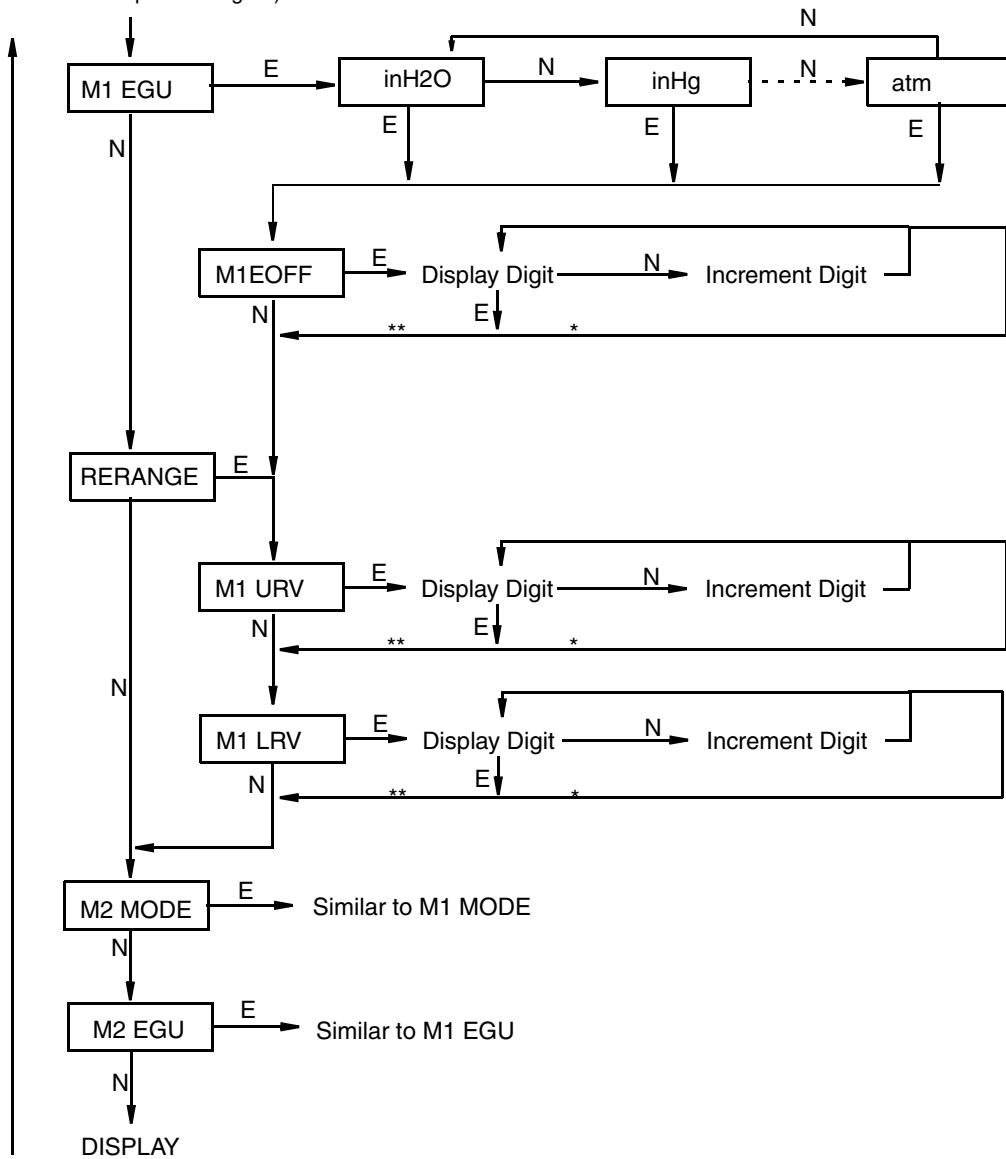


Figure 27. Configuration Structure Diagram

(continued from previous figure)



(continued on next figure)

*If character is not the last position on the display line, advances to next character.

**If character is the last position on the display line, advances to next menu item.

Figure 28. Configuration Structure Diagram (Continued)

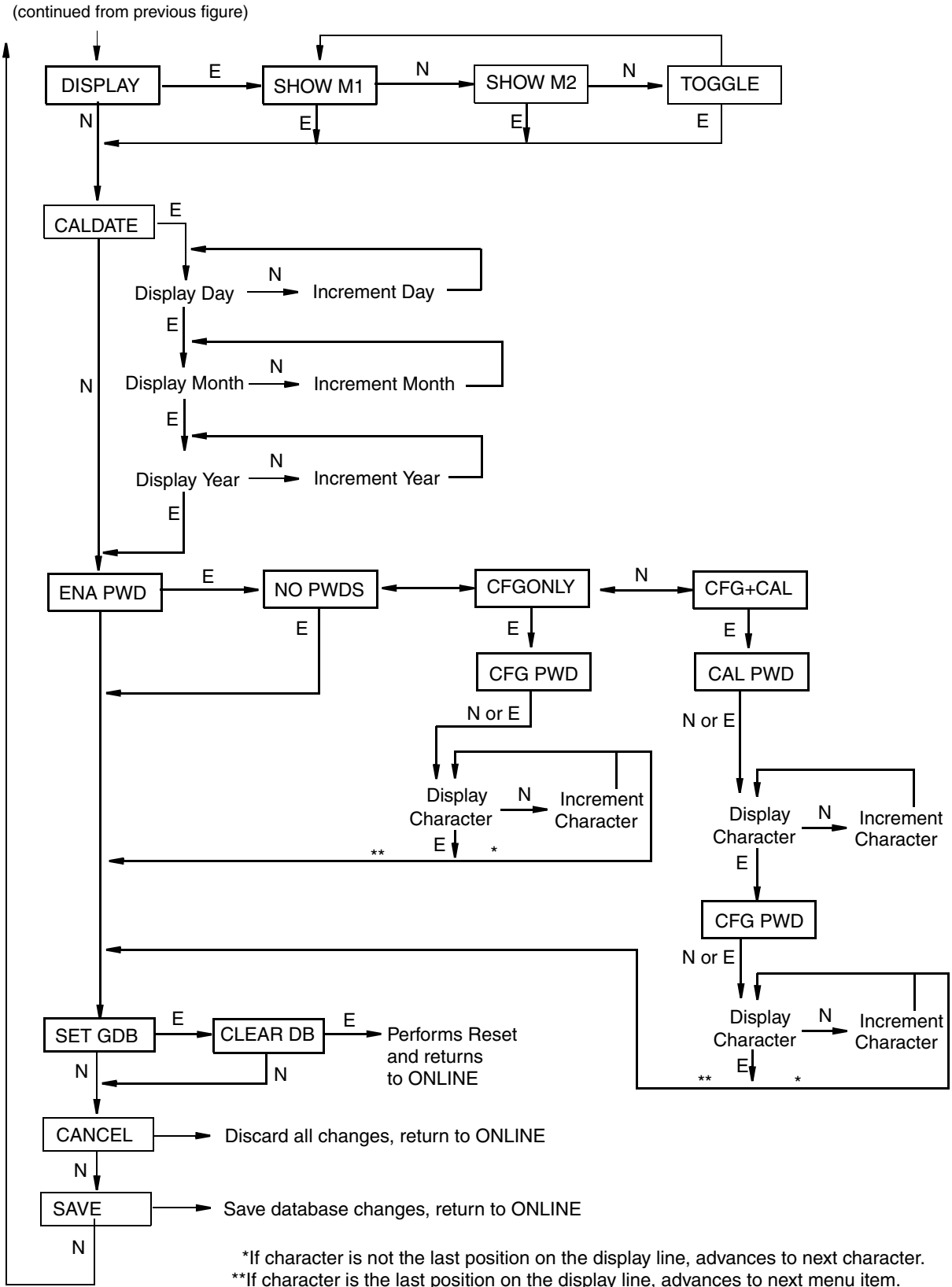


Figure 29. Configuration Structure Diagram (Continued)

Commentary on Configuration Structure Diagram

In general, use the **Next** button to select your item and the **Enter** button to specify your selection.

POLLADR:

To configure the transmitter poll address, press **Enter**. Use the **Next** button to select an address of **0** through **15**, then press **Enter**.

EX ZERO:

The External Zero feature allows the optional external zero pushbutton to be disabled for additional security. To configure this feature, go to **EX ZERO** with the **Next** button and press **Enter**. Use the **Next** button to select **EXZ DIS** or **EXZ ENA** and press **Enter**.

S2 FAIL:

To configure the temperature sensor failure strategy, go to **S2 FAIL** with the **Next** button and press **Enter**. Use the **Next** button to select **S2 FATAL** (to have the output go to that configured in **OUTFAIL**) or **S2 NOFTL** (to continue operation with a temperature sensor failure). This parameter has no effect if **POLLADR** is configured to any number from **1** through **15**.

OUT DIR:

To configure the Output Direction, go to **OUT DIR** with the **Next** button and press **Enter**. Use the **Next** button to select **OUT FWD** (4 - 20 mA) or **OUT REV** (20 - 4 mA) and press **Enter**. This parameter has no effect if **POLLADR** is configured to any number from **1** through **15**.

OUTFAIL:

The Outfail feature provides high or low output with certain malfunctions. To configure the fail mode output, go to **OUTFAIL** with the **Next** button and press **Enter**. Use the **Next** button to select **FAIL LO** or **FAIL HI** and press **Enter**. This parameter has no effect if **POLLADR** is configured to any number from **1** through **15**.

OFFL MA:

The Off-line mA feature enables you to set the output to a specified value or to the last value if the transmitter goes off-line. To configure the off-line output, go to **OFFL MA** with the **Next** button and press **Enter**. Use the **Next** button to select **LAST MA** or **USER MA** and press **Enter**. If you selected **USER MA**, press **Enter** again at the display of digits. Then use the **Next** button to step through the library of digits to select the desired first digit, then press **Enter**. Your selection is entered and the second character flashes. Repeat this procedure until you have entered the last digit. Then use the **Next** button to move the decimal point to its desired location and press **Enter**. The display advances to the next menu item.

DAMPING:

To configure additional damping, go to **DAMPING** with the **Next** button and press **Enter**. Use the **Next** button to select **NO DAMP**, **DAMP 1/4**, **DAMP 1/2**, **DAMP 1**, **DAMP 2**, **DAMP 4**, **DAMP 8**, **DAMP 16**, or **DAMP 32** and press **Enter**.

M1 MODE:

To configure the mode of the primary output, go to **M1 MODE** with the **Next** button and press **Enter**. Use the **Next** button to select **M1 LIN** and press **Enter**. **M1SQ<1C** (square root with cutoff below 1% of calibrated pressure range) or **M1SQ<4L** (square root with linear below 4% of calibrated pressure range) is not applicable to gauge pressure measurement.

M1 DISP:

To configure the optional local indicator to show engineering units or percent, go to **M1 DISP** with the **Next** button and press **Enter**. Use the **Next** button to select **M1 EGU** or **LIN PCT** and press **Enter**. **LIN PCT** only provides percent readings on the local display. The M1 engineering unit is used for remote communication of Measurement #1, even if **LIN PCT** is selected.

M1 EGU:

To configure pressure engineering units for your display and transmission, go to **M1 EGU** with the **Next** button and press **Enter**. Because **M1 MODE** is configured as **M1 LIN**, you are asked to specify one of the following pressure labels: **inH₂O**, **inHg**, **ftH₂O**, **mmH₂O**, **mmHg**, **psi**, **bar**, **mbar**, **g/cm²**, **kg/cm²**, **Pa**, **kPa**, **MPa**, **torr**, **atm**, **hW60** (inH₂O at 60°F), or **mH₂O**. Your transmitter then automatically adjusts **M1EFAC** (engineering factor), **M1 URV** (upper range value), and **M1 LRV** (lower range value). **M1EOFF** is defaulted to zero.

M1EOFF:

You can introduce an offset by entering a nonzero value for **M1EOFF**. The offset affects the value of PV that is transmitted in engineering units, transmitted as an analog mA signal, and displayed in the (optional) local display. This feature can be used in such applications as an elevated water storage tank where the transmitter is at grade level but the output is to correspond to the level of the tank. It can also be used for a grade level water storage tank where the transmitter is installed above the bottom of the tank and the output is to correspond to the level in the tank.

RERANGE:

To adjust 100% and 0% range limits, go to **RERANGE** with the **Next** button and press **Enter**. You can then adjust **M1 URV** and/or **M1 LRV** in the following two submenus.

M1 URV:

To edit the upper range value, press **Enter** at the prompt **M1 URV**. Use the procedure “Entering Numerical Values” on page 28 to edit this parameter.

M1 LRV:

Similar to **M1URV** immediately above.

M2 MODE:

M2 is a secondary measurement that is read by the HART Communicator and can be displayed on the optional display. You might use this feature to display M1 in your primary pressure units and M2 in a different set of pressure units. To configure this parameter, go to **M2 MODE** with the **Next** button and press **Enter**. Use the next button to select **M2 LIN** and press **Enter**.

M2 EGU:

Similar to M1 EGU.

DISPLAY:

To display M1, M2, or to toggle between M1 and M2, go to **DISPLAY** with the **Next** button and press **Enter**. Use the **Next** button to select **SHOW M1**, **SHOW M2**, or **TOGGLE** and press **Enter**.

CALDATE:

This is not a required entry but can be used for record-keeping or plant maintenance purposes. To edit the calibration date, go to **CALDATE** with the **Next** button and press **Enter**. You then can change the day, month, and year. The display shows the last date with the day flashing. Use the **Next** button to step through the library of digits to select the desired day, then press **Enter**. Repeat this process for the month and year.

ENA PWD:

To enable or disable the password feature, go to **ENA PWD** with the **Next** button and press **Enter**. Use the **Next** button to select **NO PWDS** (password not required for either calibration or configuration), **CFGONLY** (password required to configure but not to calibrate), or **CFG+CAL** (passwords required to both configure and calibrate) and press **Enter**.

If you selected **CFG ONLY**, the display changes to **CFG PWD**. Press either the **Next** or **Enter** button. Use the **Next** button to step through the library of characters to select the desired first character, then press **Enter**. Your selection is entered and the second character flashes. Repeat this procedure until you have created your password. If the password has less than six characters, use blanks for the remaining spaces. When you have configured the sixth space, the display advances to the next menu item.

If you selected **CFG+CAL**, the display changes to **CAL PWD**. To create the Calibration password, press either the **Next** or **Enter** button. Use the **Next** button to step through the library of characters to select the desired first character, then press **Enter**. Your selection is entered and the second character flashes. Repeat this procedure until you have created your password. If the password has less than six characters, use blanks for the remaining spaces. When you have configured the sixth space, the display advances to **CFG PWD**. Use the same procedure to create the configuration password.

— NOTE —

In normal operation, the CAL PWD allows access to only calibration mode. The CFG PWD allows access to both configuration and calibration.

— ! CAUTION —

Record your new password before saving changes to the database.

SET GDB:

If your transmitter database becomes corrupted and you receive an **INITERR** message upon startup, this function enables you to rewrite all calibration and configuration values with default values.

! CAUTION

Any calibration and configuration values that you have entered will be lost. Therefore, **SET GDB** should **not** be selected if your transmitter is functioning normally.

Character Lists

Table 9. Alphanumeric Character List

| Character List* | |
|-----------------|-----|
| @ | ‘ |
| , (comma) | (|
| A-Z (uppercase) |) |
| [| * |
| \ | + |
|] | - |
| ^ | . |
| _ (underscore) | / |
| space | 0-9 |
| ! | : |
| “ | ; |
| # | < |
| \$ | > |
| % | = |
| & | ? |

*List only applies to a HART Communicator not to optional local display.

Table 10. Numeric Character List

| Character List |
|-------------------|
| – |
| . (decimal point) |
| 0 through 9 |

Error Messages

Table 11. Configuration Error Messages

| Parameter | Condition Tested | Error Message | User Action |
|---------------------|-----------------------------|---------------|---|
| Password Protection | Password | BAD PWD | Bad password entered, use another. |
| Write Protection | Write Protection Enabled | REJECT | Displays when user attempts an action that is write protected. |
| M1EFAC | M1EFAC < 0 | -M1EFAC | Negative M1 EFAC is not valid. Change M1 EFAC to positive value. |
| | M1EFAC = 0 | 0M1EFAC | M1 EFAC = 0 is not valid. Change M1 EFAC to positive value. |
| M1 URV | M1URV > max pressure in EGU | URV>FMX | Entered pressure is greater than maximum rated pressure of transmitter. Check entry. Verify EGUs. |
| | M1URV < min pressure in EGU | URV<FMN | Entered pressure is less than minimum rated pressure of transmitter. Check entry. Verify EGUs. |
| | M1 URV = M1 LRV | LRV=URV | Cannot set span to 0. Check entry. Check M1 LRV . |
| | M1 turndown exceeds limit | BADTDWN | Check entry. Check M1 LRV . |
| M1 LRV | M1LRV > max pressure in EGU | LRV>FMX | Entered pressure is greater than maximum rated pressure of transmitter. Check entry. Verify EGUs. |
| | M1LRV < min pressure in EGU | LRV<FMN | Entered pressure is less than minimum rated pressure of transmitter. Check entry. Verify EGUs. |
| | M1 URV = M1 LRV | LRV=URV | Cannot set span to 0. Check entry. Check M1 URV . |
| | M1 turndown exceeds limit | BADTDWN | Check entry. Check M1 URV . |
| M2EFAC | M2EFAC < 0 | -M2EFAC | Negative M2 EFAC is not valid. Change M2 EFAC to positive value. |
| | M2EFAC = 0 | 0M2EFAC | M2 EFAC = 0 is not valid. Change M2 EFAC to positive value. |

6. Maintenance

—  **DANGER** —

For nonintrinsically safe installations, to prevent a potential explosion in a Division 1 hazardous area, de-energize transmitters before you remove threaded housing covers. Failure to comply with this warning could result in an explosion resulting in severe injury or death.

Error Messages

For error messages displayed on the HART Communicator refer to MI 020-366.

Parts Replacement

Parts replacement is generally limited to the electronics module assembly, housing assembly, sensor assembly, terminal block assembly, cover O-rings, and optional display. For part numbers relating to the transmitter and its options, see the following parts list:

IGP25 Gauge Pressure Transmitter: PL 009-011

IGP50 Gauge Pressure Transmitter: PL 009-012

Replacing the Terminal Block Assembly

1. Turn off transmitter power source.
2. Remove the Field Terminals and the Electronics compartment covers by rotating them counterclockwise. Screw in cover lock if applicable.
3. Remove the digital display (if applicable) as follows: grasp the two tabs on the display and rotate it about 10° in a counterclockwise direction.
4. Remove the electronics module from the housing by loosening the two captive screws that secure it to the housing. Then pull the module out of the housing far enough to gain access to the cable connectors on the rear of the module.
5. Remove the four socket head screws securing the terminal block.
6. Disconnect the terminal block cable connector from the electronics module.
7. Remove the terminal block and the gasket under it.
8. Connect the new terminal block cable connector to the electronics module.
9. Install the new terminal block and new gasket and reinstall the four screws to 0.67 N·m (6 in·lb) in several even increments.
10. Reinstall the electronics module (and digital display if applicable).
11. Reinstall the cover onto the housing by rotating it clockwise to seat the O-ring into the housing and then continue to hand tighten until the cover contacts the housing metal-to-metal. If cover locks are present, lock the cover per the procedure described in “Cover Locks” on page 21.

12. Turn on transmitter power source.

Replacing the Electronics Module Assembly

To replace the electronics module assembly, refer to Figure 30 and proceed as follows:

1. Turn off transmitter power source.
2. Remove the electronics compartment cover by rotating it counterclockwise. Screw in cover lock if applicable.
3. Remove the digital display (if applicable) as follows: grasp the two tabs on the display and rotate it about 10° in a counterclockwise direction. Pull out the display and disconnect its cable.
4. Remove the electronics module from the housing by loosening the two captive screws that secure it to the housing. Then pull the module out of the housing far enough to gain access to the cable connectors on the rear of the module.

! CAUTION

The electronics module is “one assembly” at this point and is electrically and mechanically connected to topworks with a flexible ribbon signal cable, a 2-wire power cable, and in some cases, a cable for an external zero pushbutton. Do **not** exceed the slack available in these cables when removing the assembled module.

5. Unplug all cable connectors from the rear of the electronics module and place the module on a clean surface.
6. Predetermine connector orientation, then insert the cable connectors into the replacement module. Replace the module in the housing using care not to pinch the cables between the module and the housing. Tighten the two screws that secure the module to the housing.
7. Connect the cable from the digital display to the electronics module. Ensure that the O-ring is fully seated in the display housing. Then, holding the digital display by the tabs at the sides of the display, insert it into the housing. Secure the display to the housing by aligning the tabs on the sides of the assembly and rotating it about 10° in a clockwise direction.
8. Reinstall the cover onto the housing by rotating it clockwise to seat the O-ring into the housing and then continue to hand tighten until the cover contacts the housing metal-to-metal. If cover locks are present, lock the cover per the procedure described in “Cover Locks” on page 21.
9. Turn on transmitter power source.

The module replacement procedure is now complete.

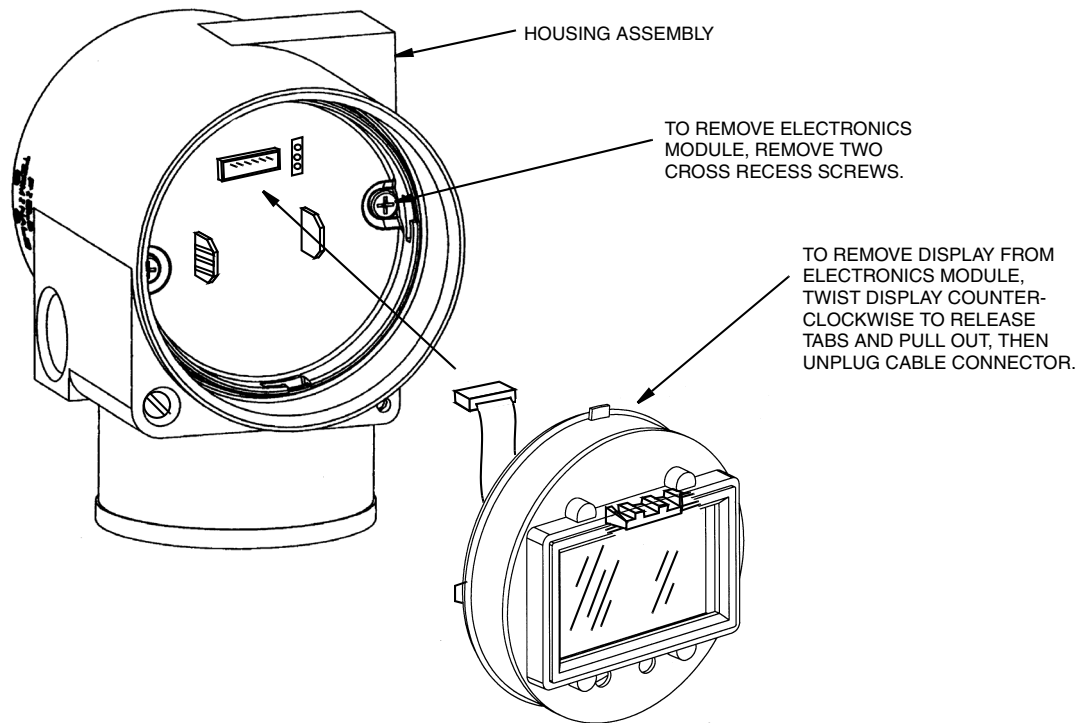


Figure 30. Replacing the Electronics Module Assembly and Display

Removing and Reinstalling a Housing Assembly

To remove and reinstall a housing assembly, refer to Figure 30 and proceed as follows:

1. Remove the electronics module per Steps 1 through 5 in the previous procedure.
2. If your housing has an anti-rotation screw, remove the red lacquer from the screw recess. Turn the screw three full turns counterclockwise.
3. If your housing has a retention clip, remove the red lacquer from the screw recess. Remove the screw completely, and slide the clip off the housing. Save the clip and screw for future use,
4. Remove the housing by rotating it counterclockwise (when viewed from the top). Use caution to avoid damaging the sensor cable.
5. Inspect the sensor O-ring for damage. If the O-ring is damaged, replace it with the appropriate O-ring. (See parts list for your transmitter). Lubricate the O-ring with silicone lubricant (Foxboro Part Number 0048130 or equivalent). Verify that the O-ring is situated in the groove of the neck.

! WARNING

Failure to reuse or install the proper O-ring for a CSA labeled product violates ANSI / ISA 12.27.01.

6. Feed the sensor cable through the housing neck into the electronics compartment.
7. Screw the housing onto the sensor neck until it bottoms. Do not over tighten. Be careful not to damage the sensor cable or dislodge the neck O-ring.

8. If your housing has an anti-rotation screw, engage the screw until it touches the sensor neck and back it off 1/8th turn. It is important that the screw is not touching the sensor. Fill the screw recess with red lacquer (Foxboro Part Number X0180GS or equivalent). The housing may then be rotated up to one full turn counterclockwise for optimum access.
9. If your housing has a retention clip, insert the clip over the boss in the housing neck so that the hole in the clip is aligned with the hole in the boss. Install the screw but do not tighten. Rotate the housing up to one full turn counterclockwise for optimum access. Tighten the retention clip screw and fill the screw recess with red lacquer (Foxboro Part Number X0180GS or equivalent). The housing can still be rotated for optimum access.
10. Reinstall the electronics module per Steps 6 through 9 in the previous procedure.

Adding the Optional Display

To add the optional display, refer to Figure 30 and proceed as follows:

1. Turn off transmitter power source.
2. Remove the electronics compartment cover by rotating it counterclockwise. Screw in cover lock if applicable.
3. Plug the display into the receptacle at the top of the electronics assembly.
4. Ensure that the O-ring is seated in its groove in the display housing. Then insert the display into the electronics compartment by grasping the two tabs on the display and rotating it about 10° in a clockwise direction.
5. Install the new cover (with a window) onto the housing by rotating it clockwise to seat the O-ring into the housing and then continue to hand tighten until the cover contacts the housing metal-to-metal. If cover locks are present, lock the cover per the procedure described in “Cover Locks” on page 21.
6. Turn on transmitter power source.

Replacing the Sensor Assembly

To replace the sensor assembly, refer to Figure 30 and proceed as follows:

1. Remove the electronics module as described above.
2. Remove the housing as described above. Sensor is left.
3. Install housing on new sensor.
4. Reinstall electronics module.

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